Average-Case Analysis and Randomization

Textbook Reading
Chapter 7 & Sections 8.4, 9.2

Overview

Design principle

- Do the easy thing and hope it works for most inputs
- Make random choices and hope they're good

Problems

- Sorting (Quick Sort)
- Permuting
- Selection
- Game tree evaluation

Quick Sort Revisited

The problem with deterministic Quick Sort:

The running time is in O(n lg n), but the algorithm for finding the pivot is non-trivial (and slow).

Quick Sort Revisited

The problem with deterministic Quick Sort:

The running time is in O(n lg n), but the algorithm for finding the pivot is non-trivial (and slow).

Remedy:

Blindly use the last element as pivot.

SimpleQuickSort(A, ℓ, r)

- 1 if $r \leq \ell$
- 2 then return
- 3 $m = Partition(A, \ell, r)$
- 4 SimpleQuickSort(A, ℓ , m 1)
- 5 SimpleQuickSort(A, m + 1, r)

```
1 \quad i = \ell - 1
```

- 2 for $j = \ell$ to r 1
- 3 do if $A[i] \leq A[r]$
- 4 then i = i + 1
- 5 swap A[i] and A[j]
- 6 swap A[i + 1] and A[r]
- 7 return i + 1

Lemma: The average-case running time of SimpleQuickSort is in O(n lg n).

Lemma: The average-case running time of SimpleQuickSort is in O(n lg n).

We defined the average-case running time of an algorithm as the average of its running time over all possible inputs of size n.

Lemma: The average-case running time of SimpleQuickSort is in O(n lg n).

We defined the average-case running time of an algorithm as the average of its running time over all possible inputs of size n.

Problem: There are infinitely many different inputs of size n!

Lemma: The average-case running time of SimpleQuickSort is in O(n lg n).

We defined the average-case running time of an algorithm as the average of its running time over all possible inputs of size n.

Problem: There are infinitely many different inputs of size n!

Observation: Simple Quick Sort behaves the same on all inputs whose elements have the same relative order.

8 | 17 | 5 | 43

2 3 1 4

Lemma: The average-case running time of SimpleQuickSort is in O(n lg n).

We defined the average-case running time of an algorithm as the average of its running time over all possible inputs of size n.

Problem: There are infinitely many different inputs of size n!

Observation: Simple Quick Sort behaves the same on all inputs whose elements have the same relative order.



 \Rightarrow The input to SimpleQuickSort is a permutation π of the sorted output sequence $\langle x_1, x_2, \ldots, x_n \rangle$ we expect as the output.

Lemma: The average-case running time of SimpleQuickSort is in O(n lg n).

We defined the average-case running time of an algorithm as the average of its running time over all possible inputs of size n.

Problem: There are infinitely many different inputs of size n!

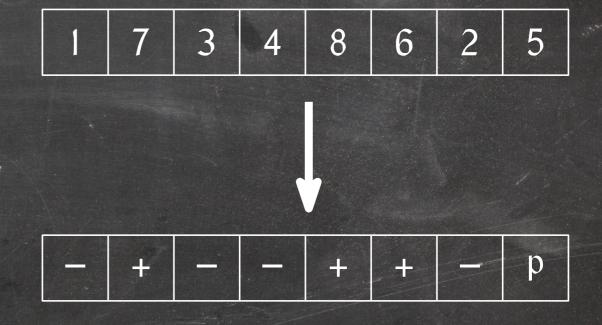
Observation: Simple Quick Sort behaves the same on all inputs whose elements have the same relative order.



- \Rightarrow The input to SimpleQuickSort is a permutation π of the sorted output sequence $\langle x_1, x_2, \ldots, x_n \rangle$ we expect as the output.
- ⇒ The average-case running time of SimpleQuickSort is the same as its expected running time on a uniformly random input permutation.

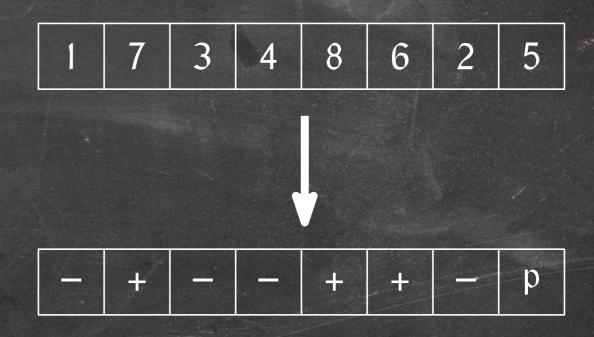
Lemma: If $A[\ell ...r]$ is a uniform random permutation of the elements in $A[\ell ...r]$, then the two subarrays $A[\ell ...m - 1]$ and A[m + 1 ...r] produced by Partition(A, ℓ , r) are also uniform random permutations of the elements they contain.

Lemma: If $A[\ell ...r]$ is a uniform random permutation of the elements in $A[\ell ...r]$, then the two subarrays $A[\ell ...m - 1]$ and A[m + 1 ...r] produced by Partition(A, ℓ , r) are also uniform random permutations of the elements they contain.



Lemma: If $A[\ell ...r]$ is a uniform random permutation of the elements in $A[\ell ...r]$, then the two subarrays $A[\ell ...m - 1]$ and A[m + 1 ...r] produced by Partition(A, ℓ , r) are also uniform random permutations of the elements they contain.

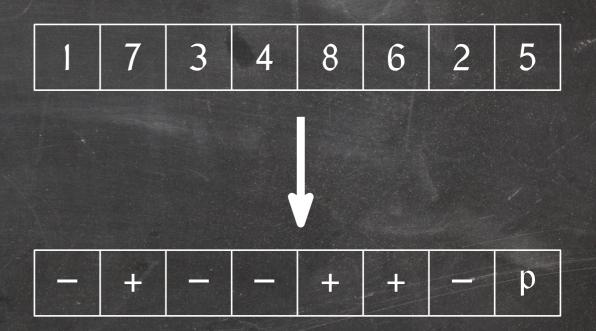
The behaviour of Partition depends only on the sequence of —s and +s!



Lemma: If $A[\ell ...r]$ is a uniform random permutation of the elements in $A[\ell ...r]$, then the two subarrays $A[\ell ...m - 1]$ and A[m + 1 ...r] produced by Partition(A, ℓ , r) are also uniform random permutations of the elements they contain.

The behaviour of Partition depends only on the sequence of —s and +s!

The -s are exactly the elements that end up in $A[\ell ... m - 1]$, the +s end up in A[m+1...r].

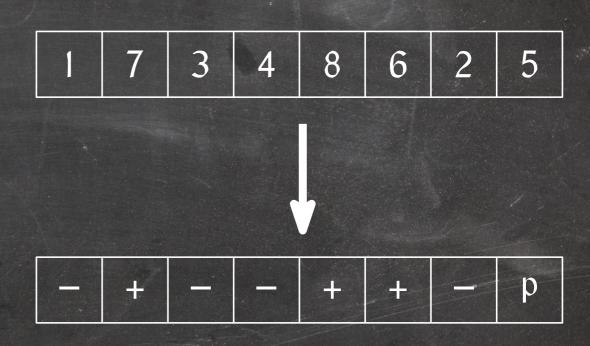


Lemma: If $A[\ell ...r]$ is a uniform random permutation of the elements in $A[\ell ...r]$, then the two subarrays $A[\ell ...m - 1]$ and A[m + 1 ...r] produced by Partition(A, ℓ , r) are also uniform random permutations of the elements they contain.

The behaviour of Partition depends only on the sequence of —s and +s!

The -s are exactly the elements that end up in $A[\ell ... m - 1]$, the +s end up in A[m+1...r].

In a uniformly random permutation, any permutation of the —s or +s is equally likely.



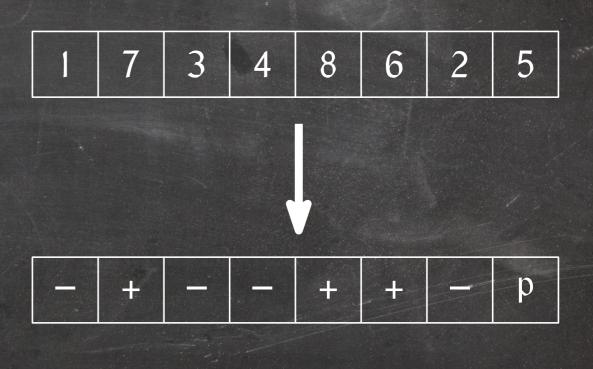
Lemma: If $A[\ell ...r]$ is a uniform random permutation of the elements in $A[\ell ...r]$, then the two subarrays $A[\ell ...m - 1]$ and A[m + 1 ...r] produced by Partition(A, ℓ , r) are also uniform random permutations of the elements they contain.

The behaviour of Partition depends only on the sequence of —s and +s!

The -s are exactly the elements that end up in $A[\ell ... m - 1]$, the +s end up in A[m+1...r].

In a uniformly random permutation, any permutation of the —s or +s is equally likely.

Each such permutation produces a different permutation of $A[\ell ...m - 1]$ or A[m+1...r].



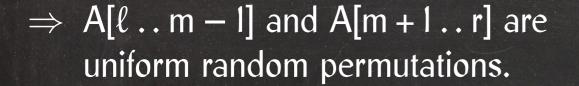
Lemma: If $A[\ell ...r]$ is a uniform random permutation of the elements in $A[\ell ...r]$, then the two subarrays $A[\ell ...m - 1]$ and A[m + 1 ...r] produced by Partition(A, ℓ , r) are also uniform random permutations of the elements they contain.

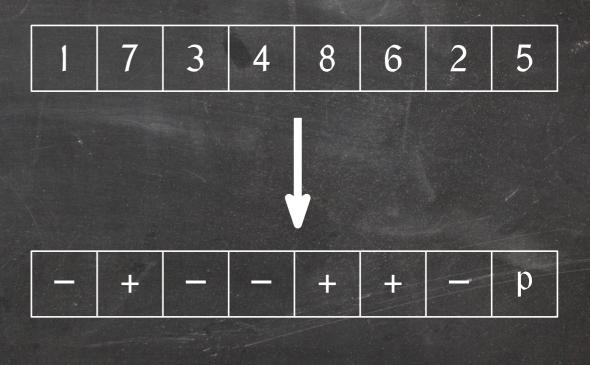
The behaviour of Partition depends only on the sequence of —s and +s!

The -s are exactly the elements that end up in $A[\ell ... m - 1]$, the +s end up in A[m+1...r].

In a uniformly random permutation, any permutation of the —s or +s is equally likely.

Each such permutation produces a different permutation of $A[\ell ...m - 1]$ or A[m+1...r].





Observation: The running time of SimpleQuickSort is in O(n + C), where C is the number of comparisons it performs between input elements.

SimpleQuickSort(A, ℓ, r)

```
1 if r \leq \ell
```

- 2 then return
- 3 $m = Partition(A, \ell, r)$
- 4 SimpleQuickSort(A, ℓ , m 1)
- 5 SimpleQuickSort(A, m + 1, r)

Partition(A, ℓ , r)

return i + 1

```
\begin{array}{ll} 1 & i=\ell-1\\ 2 & \text{for } j=\ell \text{ to } r-1\\ 3 & \text{do if } A[j] \leq A[r]\\ 4 & \text{then } i=i+1\\ 5 & \text{swap } A[i] \text{ and } A[j]\\ 6 & \text{swap } A[i+1] \text{ and } A[r] \end{array}
```

Observation: The running time of SimpleQuickSort is in O(n + C), where C is the number of comparisons it performs between input elements.

SimpleQuickSort(A, ℓ, r)

```
\begin{array}{cc} 1 & \text{if } r \leq \ell \\ 2 & \text{then return} \end{array}
```

- 3 $m = Partition(A, \ell, r)$
- 4 SimpleQuickSort(A, ℓ , m 1)
- 5 SimpleQuickSort(A, m + 1, r)

- There are O(n) recursive calls in total.
- The cost of each recursive call, excluding the call to Partition is constant.
- The cost of Partition is O(1 + # comparisons it performs).

Observation: The running time of SimpleQuickSort is in O(n + C), where C is the number of comparisons it performs between input elements.

SimpleQuickSort(A, ℓ, r)

```
\quad \text{if } r \leq \ell
```

- 2 then return
- 3 $m = Partition(A, \ell, r)$
- 4 SimpleQuickSort(A, ℓ , m 1)
- 5 SimpleQuickSort(A, m + 1, r)

- There are O(n) recursive calls in total.
- The cost of each recursive call, excluding the call to Partition is constant.
- The cost of Partition is O(1 + # comparisons it performs).
- \Rightarrow It suffices to prove that $E[C] \in O(n \lg n)$.

Observation: Two elements x_i and x_j are compared at most once.

Observation: Two elements x_i and x_j are compared at most once.

- Each call SimpleQuickSort(A, ℓ , r) compares every element in A[ℓ ..r 1] to the pivot p stored in A[r].
- The pivot is not part of the recursive calls SimpleQuickSort(A, ℓ , m 1) and SimpleQuickSort(A, m + 1, r).

SimpleQuickSort(A, ℓ, r)

```
if r \leq \ell
```

- 2 then return
- 3 $m = Partition(A, \ell, r)$
- 4 SimpleQuickSort(A, ℓ , m 1)
- 5 SimpleQuickSort(A, m + 1, r)

Observation: Two elements x_i and x_j are compared at most once.

- Each call SimpleQuickSort(A, ℓ , r) compares every element in A[ℓ ..r 1] to the pivot p stored in A[r].
- The pivot is not part of the recursive calls SimpleQuickSort(A, ℓ , m 1) and SimpleQuickSort(A, m + 1, r).

```
Let C_{ij} = \begin{cases} 1 & \text{if } x_i \text{ and and } x_j \text{ are compared} \\ 0 & \text{otherwise} \end{cases}
```

SimpleQuickSort(A, ℓ, r)

```
if r ≤ ℓ
then return
m = Partition(A, ℓ, r)
SimpleQuickSort(A, ℓ, m − 1)
SimpleQuickSort(A, m + 1, r)
```

Observation: Two elements x_i and x_j are compared at most once.

- Each call SimpleQuickSort(A, ℓ , r) compares every element in A[ℓ ..r 1] to the pivot p stored in A[r].
- The pivot is not part of the recursive calls SimpleQuickSort(A, ℓ, m − 1) and SimpleQuickSort(A, m + 1, r).

Let
$$C_{ij} = \begin{cases} 1 & \text{if } x_i \text{ and and } x_j \text{ are compared} \\ 0 & \text{otherwise} \end{cases}$$
.

$$\Rightarrow C = \sum_{i,j} C_{ij}$$

SimpleQuickSort(A, ℓ, r)

```
if r \leq \ell
```

- 2 then return
- 3 $m = Partition(A, \ell, r)$
- 4 SimpleQuickSort(A, ℓ , m 1)
- 5 SimpleQuickSort(A, m + 1, r)

```
1 \quad i = \ell - 1
```

- 2 for $j = \ell$ to r 1
- 3 do if $A[j] \leq A[r]$
- 4 then i = i+1
- 5 swap A[i] and A[j]
- 6 swap A[i + 1] and A[r]
- 7 return i + 1

Observation: Two elements x_i and x_j are compared at most once.

- Each call SimpleQuickSort(A, ℓ , r) compares every element in A[ℓ ..r 1] to the pivot p stored in A[r].
- The pivot is not part of the recursive calls SimpleQuickSort(A, ℓ , m 1) and SimpleQuickSort(A, m + 1, r).

Let
$$C_{ij} = \begin{cases} 1 & \text{if } x_i \text{ and and } x_j \text{ are compared} \\ 0 & \text{otherwise} \end{cases}$$
.

$$\Rightarrow C = \sum_{i,j} C_{ij}$$

$$\Rightarrow E[C] = E\left[\sum_{i,j} C_{ij}\right] = \sum_{i,j} E[C_{ij}]$$

SimpleQuickSort(A, ℓ, r)

```
if r \leq \ell
```

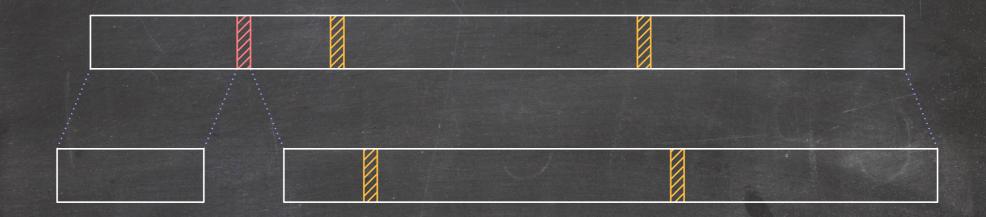
- 2 then return
- 3 $m = Partition(A, \ell, r)$
- 4 SimpleQuickSort(A, ℓ , m 1)
- 5 SimpleQuickSort(A, m + 1, r)

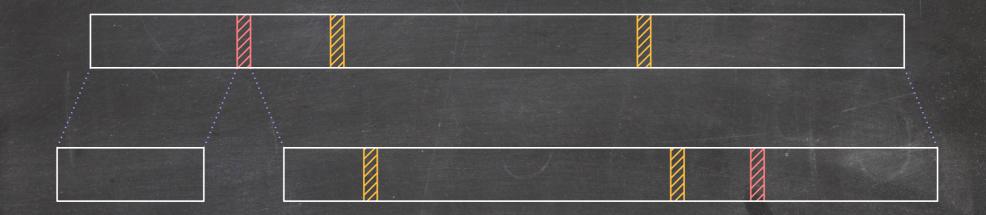
```
1 \quad i = \ell - 1
```

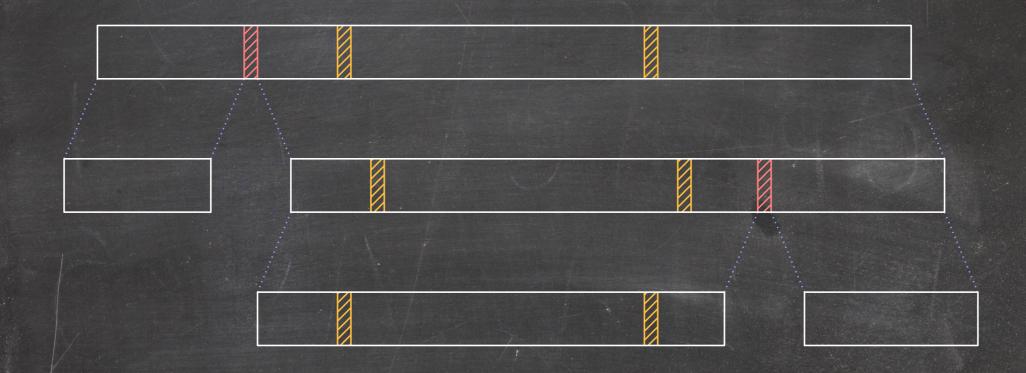
- 2 for $j = \ell$ to r 1
- 3 do if $A[j] \leq A[r]$
- 4 then i = i + 1
- 5 swap A[i] and A[j]
- 6 swap A[i + 1] and A[r]
- 7 return i + 1

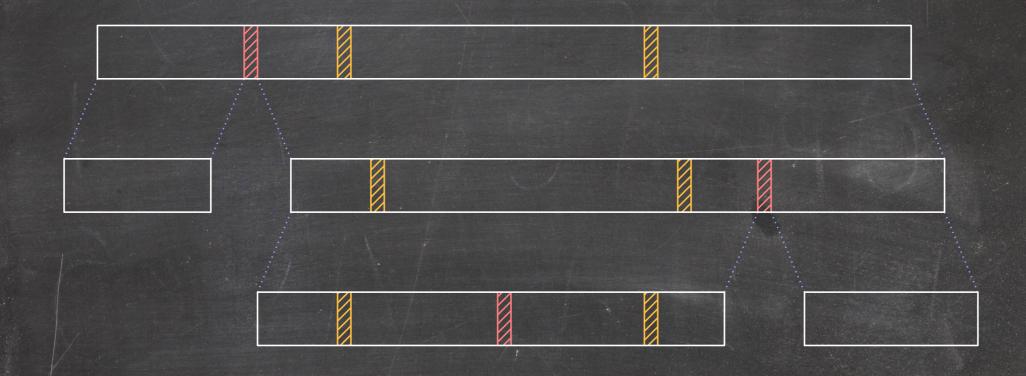


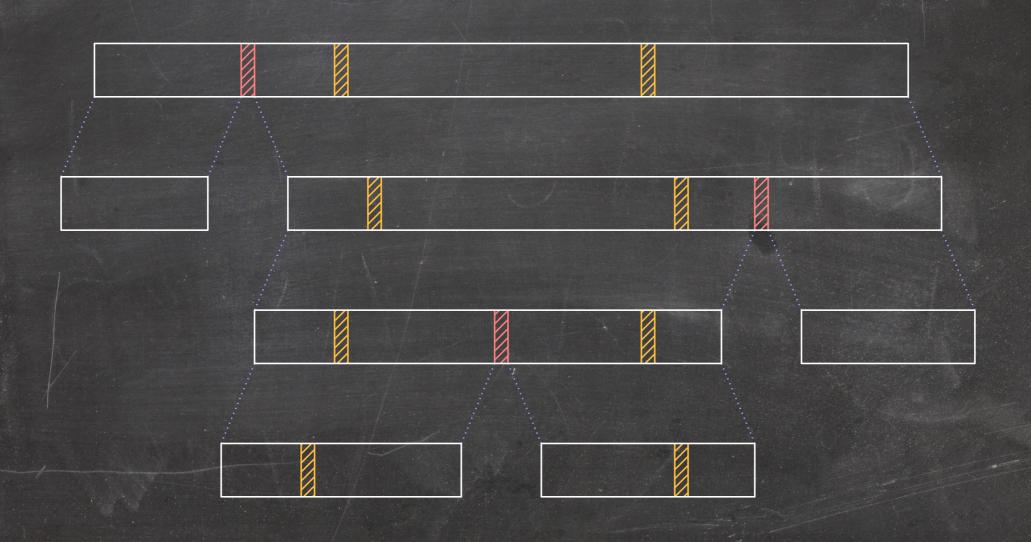


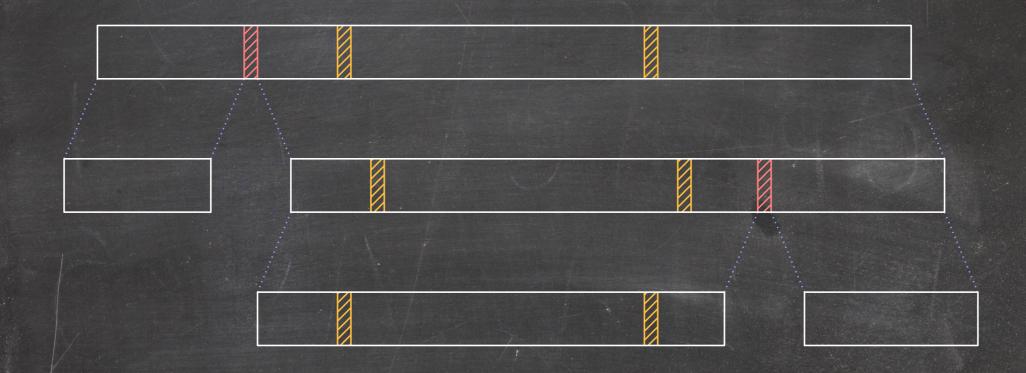


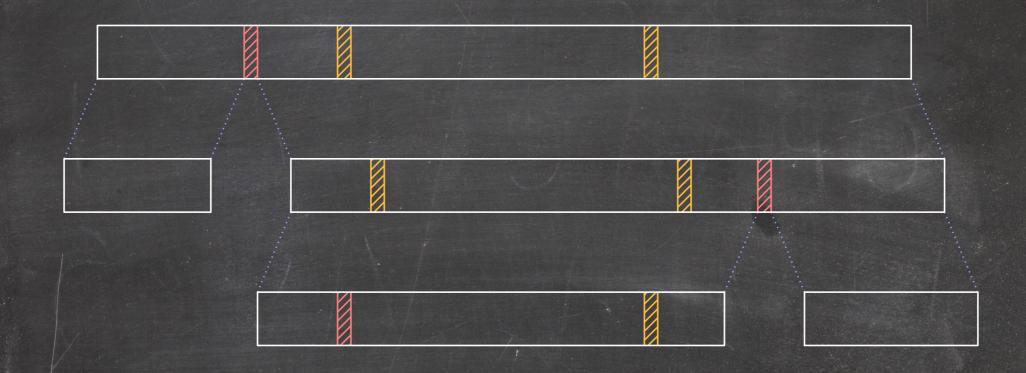














Corollary:
$$E[C_{ij}] = \frac{2}{j-i+1}$$
.

$$E[C] = \sum_{i=1}^{n-1} \sum_{j=i+1}^{n} E[C_{ij}]$$

$$E[C] = \sum_{i=1}^{n-1} \sum_{j=i+1}^{n} E[C_{ij}]$$

$$= \sum_{i=1}^{n-1} \sum_{j=i+1}^{n} \frac{2}{j-i+1}$$

$$E[C] = \sum_{i=1}^{n-1} \sum_{j=i+1}^{n} E[C_{ij}]$$

$$= \sum_{i=1}^{n-1} \sum_{j=i+1}^{n} \frac{2}{j-i+1}$$

$$= \sum_{i=1}^{n-1} \sum_{k=1}^{n-i} \frac{2}{k+1}$$

$$E[C] = \sum_{i=1}^{n-1} \sum_{j=i+1}^{n} E[C_{ij}]$$

$$= \sum_{i=1}^{n-1} \sum_{j=i+1}^{n} \frac{2}{j-i+1}$$

$$= \sum_{i=1}^{n-1} \sum_{k=1}^{n-i} \frac{2}{k+1}$$

$$< 2 \sum_{i=1}^{n-1} \sum_{k=1}^{n} \frac{1}{k}$$

$$E[C] = \sum_{i=1}^{n-1} \sum_{j=i+1}^{n} E[C_{ij}]$$

$$= \sum_{i=1}^{n-1} \sum_{j=i+1}^{n} \frac{2}{j-i+1}$$

$$= \sum_{i=1}^{n-1} \sum_{k=1}^{n-i} \frac{2}{k+1}$$

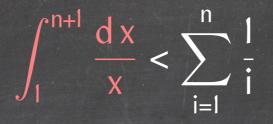
$$< 2 \sum_{i=1}^{n-1} \sum_{k=1}^{n} \frac{1}{k}$$

$$= 2(n-1)H_n.$$

$$H_n = \sum_{i=1}^n \frac{1}{i}$$
 = nth Harmonic Number









$$ln(n+1) = \int_1^{n+1} \frac{dx}{x} < \sum_{i=1}^n \frac{1}{i}$$



$$\ln(n+1) = \int_{1}^{n+1} \frac{dx}{x} < \sum_{i=1}^{n} \frac{1}{i} < 1 + \int_{1}^{n} \frac{dx}{x}$$



$$\ln(n+1) = \int_{1}^{n+1} \frac{dx}{x} < \sum_{i=1}^{n} \frac{1}{i} < 1 + \int_{1}^{n} \frac{dx}{x} = 1 + \ln n$$



$$\ln(n+1) = \int_{1}^{n+1} \frac{dx}{x} < \sum_{i=1}^{n} \frac{1}{i} < 1 + \int_{1}^{n} \frac{dx}{x} = 1 + \ln n$$



$$\Rightarrow$$
 E[C] \leq 2(n - I)H_n \in O(n lg n)

Algorithms that are fast in the worst case are the gold standard but are difficult to design and often have higher constant factors than algorithms that are efficient on average.

Algorithms that are fast in the worst case are the gold standard but are difficult to design and often have higher constant factors than algorithms that are efficient on average.

Worst-case efficiency is desirable if we need performance guarantees every single time we run the algorithm.

Algorithms that are fast in the worst case are the gold standard but are difficult to design and often have higher constant factors than algorithms that are efficient on average.

Worst-case efficiency is desirable if we need performance guarantees every single time we run the algorithm.

Algorithms that are fast on average are often simpler and on average faster than worst-case efficient algorithms.

Algorithms that are fast in the worst case are the gold standard but are difficult to design and often have higher constant factors than algorithms that are efficient on average.

Worst-case efficiency is desirable if we need performance guarantees every single time we run the algorithm.

Algorithms that are fast on average are often simpler and on average faster than worst-case efficient algorithms.

They are a good choice when we want good performance most of the time and possibly averaged over running the algorithm many times.

What exactly is the meaning of the following statement?

"The average-case running time of algorithm A is T(n)."

What exactly is the meaning of the following statement?

"The average-case running time of algorithm A is T(n)."

"If every input is equally likely, then we expect to see a running time of T(n) on average."

What exactly is the meaning of the following statement?

"The average-case running time of algorithm A is T(n)."

"If every input is equally likely, then we expect to see a running time of T(n) on average."

This assumption may not be true in some applications, invalidating the performance prediction we obtain using average-case analysis!

What exactly is the meaning of the following statement?

"The average-case running time of algorithm A is T(n)."

"If every input is equally likely, then we expect to see a running time of T(n) on average."

This assumption may not be true in some applications, invalidating the performance prediction we obtain using average-case analysis!

Example:

SimpleQuickSort takes $\Theta(n^2)$ time on almost sorted inputs.

There are applications where the inputs to be sorted are all almost sorted.

SimpleQuickSort is a poor choice of a sorting algorithm in such applications.

Average-case analysis is applied to a deterministic algorithm and assumes randomness in the input.

Average-case analysis is applied to a deterministic algorithm and assumes randomness in the input.

A randomized algorithm makes no assumptions about the input and ensures randomness by making random choices.

Average-case analysis is applied to a deterministic algorithm and assumes randomness in the input.

A randomized algorithm makes no assumptions about the input and ensures randomness by making random choices.

Since a randomized algorithm behaves differently every time it runs, there is no way to force it to exhibit its worst-case running time!

Average-case analysis is applied to a deterministic algorithm and assumes randomness in the input.

A randomized algorithm makes no assumptions about the input and ensures randomness by making random choices.

Since a randomized algorithm behaves differently every time it runs, there is no way to force it to exhibit its worst-case running time!

The expected running time of a randomized algorithm is an expectation over the random choices the algorithm makes.

Average-case analysis is applied to a deterministic algorithm and assumes randomness in the input.

A randomized algorithm makes no assumptions about the input and ensures randomness by making random choices.

Since a randomized algorithm behaves differently every time it runs, there is no way to force it to exhibit its worst-case running time!

The expected running time of a randomized algorithm is an expectation over the random choices the algorithm makes.

⇒ No more assumptions about the probability distribution. We know the distribution of the choices the algorithm makes.

The expected running time of SimpleQuickSort on a uniform random permutation is in O(n lg n).

The expected running time of SimpleQuickSort on a uniform random permutation is in O(n lg n).

So why don't we just ensure the input is a uniform random permutation?

RandomPermutationQuickSort(A)

- RandomPermute(A)
- 2 SimpleQuickSort(A, I, n)

The expected running time of SimpleQuickSort on a uniform random permutation is in O(n lg n).

So why don't we just ensure the input is a uniform random permutation?

RandomPermutationQuickSort(A)

- | RandomPermute(A)
- 2 SimpleQuickSort(A, I, n)

We can compute a uniform random permutation in O(n) time in the worst case.

The expected running time of SimpleQuickSort on a uniform random permutation is in O(n lg n).

So why don't we just ensure the input is a uniform random permutation?

RandomPermutationQuickSort(A)

- RandomPermute(A)
- 2 SimpleQuickSort(A, I, n)

We can compute a uniform random permutation in O(n) time in the worst case.

Corollary: The expected running time of RandomPermutationQuickSort is in O(n lg n).

Randomized Quick Sort, Take 2 The key to the analysis of SimpleQuickSort:

The key to the analysis of SimpleQuickSort:

If the input is a uniform random permutation, then any element is equally likely to be chosen as pivot.

The key to the analysis of SimpleQuickSort:

If the input is a uniform random permutation, then any element is equally likely to be chosen as pivot.

So why don't we make sure we choose a uniform random pivot, no matter the input permutation?

RandomPivotQuickSort(A, ℓ, r)

```
1 if r ≤ ℓ
2 then return
3 p = RandomNumber(ℓ, r)
4 swap A[p] and A[r]
5 m = Partition(A, ℓ, r)
6 RandomPivotQuickSort(A, ℓ, m − 1)
```

RandomPivotQuickSort(A, m + 1, r)

The key to the analysis of SimpleQuickSort:

If the input is a uniform random permutation, then any element is equally likely to be chosen as pivot.

So why don't we make sure we choose a uniform random pivot, no matter the input permutation?

RandomPivotQuickSort(A, ℓ, r)

```
1 if r ≤ ℓ
2 then return
3 p = RandomNumber(ℓ, r)
4 swap A[p] and A[r]
5 m = Partition(A, ℓ, r)
6 RandomPivotQuickSort(A, ℓ, m − 1)
7 RandomPivotQuickSort(A, m + 1, r)
```

Lemma: The expected running time of RandomPivotQuickSort is in O(n lg n).

The analysis is 100% identical to that of SimpleQuickSort!

```
1 n = |A|

2 for j = n downto 2

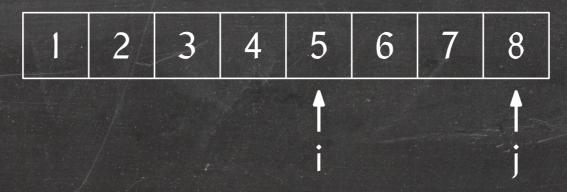
3 do i = RandomNumber(I, n)

4 swap A[i] and A[j]
```

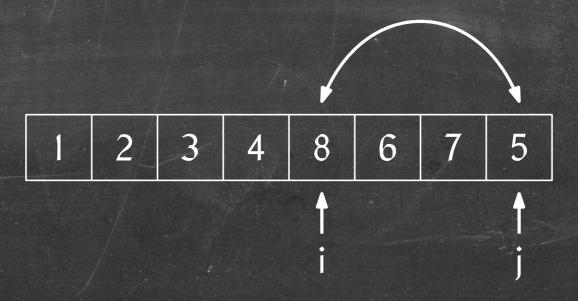
```
    1  n = |A|
    2  for j = n downto 2
    3  do i = RandomNumber(I, n)
    4  swap A[i] and A[j]
```



```
    1  n = |A|
    2  for j = n downto 2
    3  do i = RandomNumber(I, n)
    4  swap A[i] and A[j]
```



```
    1  n = |A|
    2  for j = n downto 2
    3  do i = RandomNumber(1, n)
    4  swap A[i] and A[j]
```



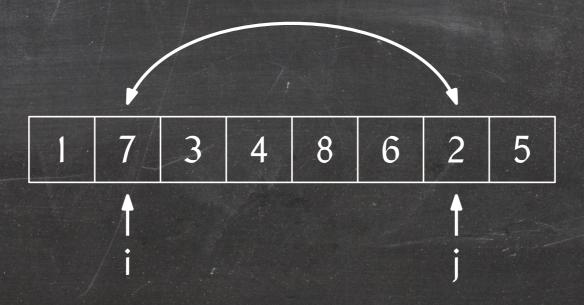
```
    1  n = |A|
    2  for j = n downto 2
    3  do i = RandomNumber(I, n)
    4  swap A[i] and A[j]
```



```
    1  n = |A|
    2  for j = n downto 2
    3  do i = RandomNumber(I, n)
    4  swap A[i] and A[j]
```



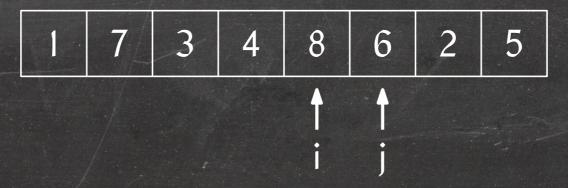
```
    1  n = |A|
    2  for j = n downto 2
    3  do i = RandomNumber(I, n)
    4  swap A[i] and A[j]
```

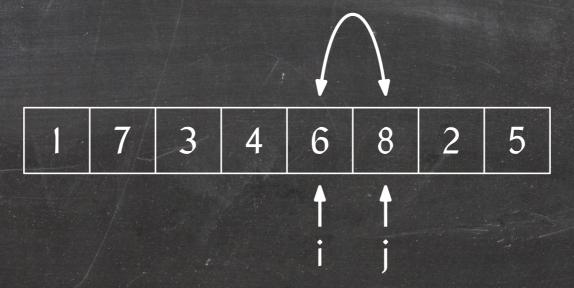


```
    1  n = |A|
    2  for j = n downto 2
    3  do i = RandomNumber(I, n)
    4  swap A[i] and A[j]
```



```
    1  n = |A|
    2  for j = n downto 2
    3  do i = RandomNumber(I, n)
    4  swap A[i] and A[j]
```





RandomPermute(A)

```
    1  n = |A|
    2  for j = n downto 2
    3  do i = RandomNumber(I, n)
    4  swap A[i] and A[j]
```

Observation: RandomPermute takes O(n) time.

RandomPermute(A)

```
    1  n = |A|
    2  for j = n downto 2
    3  do i = RandomNumber(I, n)
    4  swap A[i] and A[j]
```

Observation: RandomPermute takes O(n) time.

Lemma: RandomPermute produces each permutation of the input array A with probability $\frac{1}{n!}$.

RandomPermute(A)

```
    1  n = |A|
    2  for j = n downto 2
    3  do i = RandomNumber(I, n)
    4  swap A[i] and A[j]
```

Observation: RandomPermute takes O(n) time.

Lemma: RandomPermute produces each permutation of the input array A with probability $\frac{1}{n!}$.

Induction on n.

RandomPermute(A)

```
    1  n = |A|
    2  for j = n downto 2
    3  do i = RandomNumber(I, n)
    4  swap A[i] and A[j]
```

Observation: RandomPermute takes O(n) time.

Lemma: RandomPermute produces each permutation of the input array A with probability $\frac{1}{n!}$.

Induction on n.

If n = 1, then it produces the only possible permutation with probability $1 = \frac{1}{1!}$.

RandomPermute(A)

```
    1 n = |A|
    2 for j = n downto 2
    3 do i = RandomNumber(I, n)
    4 swap A[i] and A[j]
```

Observation: RandomPermute takes O(n) time.

Lemma: RandomPermute produces each permutation of the input array A with probability $\frac{1}{n!}$.

If n > 1, then to produce the permutation $\langle x_1, x_2, \dots, x_n \rangle$ (event E), we need to

- Place x_n into A[n] (event E_1) and
- Place $x_1, x_2, ..., x_{n-1}$ into A[1...n 1] (event E₂).

RandomPermute(A)

```
    1 n = |A|
    2 for j = n downto 2
    3 do i = RandomNumber(I, n)
    4 swap A[i] and A[j]
```

Observation: RandomPermute takes O(n) time.

Lemma: RandomPermute produces each permutation of the input array A with probability $\frac{1}{n!}$.

If n > 1, then to produce the permutation $\langle x_1, x_2, \dots, x_n \rangle$ (event E), we need to

- Place x_n into A[n] (event E_1) and
- Place $x_1, x_2, ..., x_{n-1}$ into A[1...n 1] (event E₂).

So
$$P[E] = P[E_1 \cap E_2] = P[E_1] \cdot P[E_2|E_1] = \frac{1}{n} \cdot \frac{1}{(n-1)!} = \frac{1}{n!}$$
.

RandomizedSelection(A, ℓ , r, k)

```
1 if r \le \ell

2 then return A[\ell]

3 p = RandomNumber(\ell, r)

4 swap A[p] and A[r]

5 m = Partition(A, \ell, r)

6 if m - \ell = k - 1

7 then return A[m]

8 else if m - \ell \ge k

9 then RandomizedSelection(A, \ell, m - 1, k)

10 else RandomizedSelection(A, m + 1, m - 1, k)
```

RandomizedSelection(A, ℓ , r, k)

```
1 if r \le \ell

2 then return A[\ell]

3 p = RandomNumber(\ell, r)

4 swap A[p] and A[r]

5 m = Partition(A, \ell, r)

6 if m - \ell = k - 1

7 then return A[m]

8 else if m - \ell \ge k

9 then RandomizedSelection(A, \ell, m - 1, k)

10 else RandomizedSelection(A, m + 1, m - 1, k)
```

Lemma: The expected running time of RandomizedSelection is in O(n).

Observation: If we choose the ith smallest element as pivot, then

$$E[T(n)] \le O(n) + E[T(max(n-i,i-l))].$$

Observation: If we choose the ith smallest element as pivot, then

$$E[T(n)] \le O(n) + E[T(max(n - i, i - 1))].$$

Corollary:
$$E[T(n)] \le O(n) + \frac{1}{n} \sum_{i=1}^{n} E[T(max(n-i,i-1))].$$

Observation: If we choose the ith smallest element as pivot, then

$$E[T(n)] \le O(n) + E[T(max(n - i, i - 1))].$$

Corollary:
$$E[T(n)] \le O(n) + \frac{1}{n} \sum_{i=1}^{n} E[T(\max(n-i,i-1))].$$

Claim: $E[T(n)] \le cn$, for some c > 0.

Observation: If we choose the ith smallest element as pivot, then

$$E[T(n)] \le O(n) + E[T(max(n - i, i - 1))].$$

Corollary:
$$E[T(n)] \le O(n) + \frac{1}{n} \sum_{i=1}^{n} E[T(\max(n-i,i-1))].$$

Claim: $E[T(n)] \le cn$, for some c > 0.

Base case: $1 \le n < 4$.

 $T(n) \le c \le cn$.

$$E[T(n)] \le an + \frac{1}{n} \sum_{i=1}^{n} E[T(max(i-1, n-i))]$$

$$\begin{aligned} & E[T(n)] \leq an + \frac{1}{n} \sum_{i=1}^{n} E[T(max(i-1,n-i))] \\ & \leq an + \frac{2}{n} \sum_{i=\lfloor n/2 \rfloor}^{n-1} E[T(i)] \end{aligned}$$

$$\begin{split} & E[T(n)] \leq an + \frac{1}{n} \sum_{i=1}^{n} E[T(max(i-1,n-i))] \\ & \leq an + \frac{2}{n} \sum_{i=\lfloor n/2 \rfloor}^{n-1} E[T(i)] \\ & \leq an + \frac{2}{n} \sum_{i=\lfloor n/2 \rfloor}^{n-1} ci \end{split}$$

$$\begin{split} & E[T(n)] \leq an + \frac{1}{n} \sum_{i=1}^{n} E[T(max(i-1,n-i))] \\ & \leq an + \frac{2}{n} \sum_{i=\lfloor n/2 \rfloor}^{n-1} E[T(i)] \\ & \leq an + \frac{2}{n} \sum_{i=\lfloor n/2 \rfloor}^{n-1} ci \\ & = an + \frac{2c}{n} \left(\sum_{i=1}^{n-1} i - \sum_{i=1}^{\lfloor n/2 \rfloor -1} i \right) \end{split}$$

$$\begin{split} & E[T(n)] \leq an + \frac{1}{n} \sum_{i=1}^{n} E[T(max(i-1,n-i))] \\ & \leq an + \frac{2}{n} \sum_{i=\lfloor n/2 \rfloor}^{n-1} E[T(i)] \\ & \leq an + \frac{2}{n} \sum_{i=\lfloor n/2 \rfloor}^{n-1} ci \\ & = an + \frac{2c}{n} \left(\sum_{i=1}^{n-1} i - \sum_{i=1}^{\lfloor n/2 \rfloor - 1} i \right) \\ & = an + \frac{2c}{n} \left(\frac{n(n-1)}{2} - \frac{\lfloor n/2 \rfloor (\lfloor n/2 \rfloor - 1)}{2} \right) \end{split}$$

$$\begin{split} E[T(n)] & \leq an + \frac{1}{n} \sum_{i=1}^{n} E[T(max(i-1,n-i))] \\ & \leq an + \frac{2}{n} \sum_{i=\lfloor n/2 \rfloor}^{n-1} E[T(i)] \\ & \leq an + \frac{2}{n} \sum_{i=\lfloor n/2 \rfloor}^{n-1} ci \\ & = an + \frac{2c}{n} \left(\sum_{i=1}^{n-1} i - \sum_{i=1}^{\lfloor n/2 \rfloor - 1} i \right) \\ & = an + \frac{2c}{n} \left(\frac{n(n-1)}{2} - \frac{\lfloor n/2 \rfloor (\lfloor n/2 \rfloor - 1)}{2} \right) \\ & \leq an + \frac{c}{n} \left[n(n-1) - \left(\frac{n}{2} - 1 \right) \left(\frac{n}{2} - 2 \right) \right] \end{split}$$

$$\begin{aligned} & E[T(n)] \leq an + \frac{1}{n} \sum_{i=1}^{n} E[T(max(i-1,n-i))] \\ & \leq an + \frac{c}{n} \left[n(n-1) - \left(\frac{n}{2} - 1 \right) \left(\frac{n}{2} - 2 \right) \right] \end{aligned}$$

$$\begin{split} E[T(n)] &\leq an + \frac{1}{n} \sum_{i=1}^{n} E[T(max(i-1,n-i))] \\ &\leq an + \frac{c}{n} \left[n(n-1) - \left(\frac{n}{2} - 1 \right) \left(\frac{n}{2} - 2 \right) \right] \\ &= an + \frac{c}{n} \left(\frac{3n^2}{4} + \frac{n}{2} \right) \end{split}$$

$$\begin{split} & E[T(n)] \leq an + \frac{1}{n} \sum_{i=1}^{n} E[T(max(i-1,n-i))] \\ & \leq an + \frac{c}{n} \left[n(n-1) - \left(\frac{n}{2} - 1 \right) \left(\frac{n}{2} - 2 \right) \right] \\ & = an + \frac{c}{n} \left(\frac{3n^2}{4} + \frac{n}{2} \right) \\ & = \left(a + \frac{3c}{4} + \frac{c}{2n} \right) n \end{split}$$

$$\begin{split} & E[T(n)] \leq an + \frac{1}{n} \sum_{i=1}^{n} E[T(max(i-1,n-i))] \\ & \leq an + \frac{c}{n} \left[n(n-1) - \left(\frac{n}{2} - 1 \right) \left(\frac{n}{2} - 2 \right) \right] \\ & = an + \frac{c}{n} \left(\frac{3n^2}{4} + \frac{n}{2} \right) \\ & = \left(a + \frac{3c}{4} + \frac{c}{2n} \right) n \\ & \leq cn \quad \forall c \geq 8a. \end{split}$$

Using comparisons only, as Insertion Sort, Merge Sort, Quick Sort do, it is impossible to sort faster than in $\Omega(n \lg n)$ time.

Using comparisons only, as Insertion Sort, Merge Sort, Quick Sort do, it is impossible to sort faster than in $\Omega(n \lg n)$ time.

By exploiting assumptions about the input and using element values in the algorithm, we can do better:

Using comparisons only, as Insertion Sort, Merge Sort, Quick Sort do, it is impossible to sort faster than in $\Omega(n \lg n)$ time.

By exploiting assumptions about the input and using element values in the algorithm, we can do better:

Counting sort: Sorts n integers between 1 and n in O(n) time.

Using comparisons only, as Insertion Sort, Merge Sort, Quick Sort do, it is impossible to sort faster than in $\Omega(n \lg n)$ time.

By exploiting assumptions about the input and using element values in the algorithm, we can do better:

Counting sort: Sorts n integers between I and n in O(n) time.

Radix sort: Sorts n integers between I and n^c in O(cn) time. This is O(n) if c is a constant.

Using comparisons only, as Insertion Sort, Merge Sort, Quick Sort do, it is impossible to sort faster than in $\Omega(n \lg n)$ time.

By exploiting assumptions about the input and using element values in the algorithm, we can do better:

Counting sort: Sorts n integers between I and n in O(n) time.

Radix sort: Sorts n integers between I and n^c in O(cn) time. This is O(n) if c is a constant.

Bucket sort: Sorts n real numbers drawn uniformly at random from an interval [a, b) in expected linear time.

Bucket Sort

Assume the inputs are real numbers drawn uniformly at random from some interval [a, b).



Bucket Sort

Assume the inputs are real numbers drawn uniformly at random from some interval [a, b).



We can normalize this to the interval [0, 1).



Bucket Sort

Assume the inputs are real numbers drawn uniformly at random from some interval [a, b).



We can normalize this to the interval [0, 1).

Divide [0, 1) into subintervals of length $\frac{1}{n}$.



Assume the inputs are real numbers drawn uniformly at random from some interval [a, b).



We can normalize this to the interval [0, 1).

Divide [0, 1) into subintervals of length $\frac{1}{n}$.



How many elements do we expect to end up in each subinterval?

Assume the inputs are real numbers drawn uniformly at random from some interval [a, b).



We can normalize this to the interval [0, 1).

Divide [0, 1) into subintervals of length $\frac{1}{n}$.



How many elements do we expect to end up in each subinterval? !!

Assume the inputs are real numbers drawn uniformly at random from some interval [a, b).



We can normalize this to the interval [0, 1).

Divide [0, 1) into subintervals of length $\frac{1}{n}$.



How many elements do we expect to end up in each subinterval? !!

- \Rightarrow Strategy:
 - Bucket items according to the subinterval they belong to.
 - Sort each bucket, hopefully in constant time.
 - Concatenate the sorted buckets.

BucketSort(A)

```
1 n = |A|
2 B = \text{an array of n empty singly-linked lists}
3 \textbf{for } i = 1 \text{ to n}
4 \textbf{do prepend A[i] to list B[1 + \lfloor n \cdot A[i] \rfloor]}
5 \textbf{for } i = 1 \text{ to n}
6 \textbf{do InsertionSort(B[i])}
7 j = 0
8 \textbf{for } i = 1 \text{ to n}
9 \textbf{do for every element } x \in B[i]
10 \textbf{do A[j]} = x
11 j = j + 1
```

BucketSort(A)

```
1 n = |A|
2 B = \text{an array of n empty singly-linked lists}
3 for i = 1 \text{ to n}
4 do prepend A[i] to list B[1 + \lfloor n \cdot A[i] \rfloor]
5 for i = 1 \text{ to n}
6 do InsertionSort(B[i])
7 j = 0
8 for i = 1 \text{ to n}
9 do for every element x \in B[i]
10 do A[j] = x
11 j = j + 1
```

This is where we depart from using comparisons only!

BucketSort(A)

```
1 n = |A|
2 B = \text{an array of n empty singly-linked lists}
3 for i = 1 \text{ to n}
4 do prepend A[i] to list B[1 + \lfloor n \cdot A[i] \rfloor]
5 for i = 1 \text{ to n}
6 do InsertionSort(B[i])
7 j = 0
8 for i = 1 \text{ to n}
9 do for every element x \in B[i]
10 do A[j] = x
11 j = j + 1
```

This is where we depart from using comparisons only!

Worst-case running time: O(n²)

BucketSort(A)

```
1 \quad n = |A|
                                                          This is where we depart
    B = an array of n empty singly-linked lists
                                                          from using comparisons
    for i = 1 to n
                                                          only!
       do prepend A[i] to list B[1 + |n \cdot A[i]|]
    for i = 1 to n
      do InsertionSort(B[i])
                                                Why not Merge Sort?
    j = 0
    for i = 1 to n
       do for every element x \in B[i]
10
              do A[j] = x
                j = j + 1
```

Worst-case running time: O(n²)

BucketSort(A)

```
n = |A|
                                                          This is where we depart
    B = an array of n empty singly-linked lists
                                                          from using comparisons
    for i = 1 to n
                                                          only!
       do prepend A[i] to list B[1 + |n \cdot A[i]|]
    for i = 1 to n
       do InsertionSort(B[i])
                                               Why not Merge Sort?
    j = 0
                                               It only helps in the worst case.
    for i = 1 to n
       do for every element x \in B[i]
                                               It's more complicated.
10
              do A[j] = x
                                               It actually hurts when buckets are
                 j = j + 1
                                               small, which is what we expect.
```

Worst-case running time: O(n²)

Running time:
$$T(n) \in O\left(n + \sum_{i=1}^{n} n_i^2\right)$$

 n_i = the number of elements in B[i]

Running time:
$$T(n) \in O\left(n + \sum_{i=1}^{n} n_i^2\right)$$

 n_i = the number of elements in B[i]

$$E[T(n)] \in O\left(n + \sum_{i=1}^n E[n_i]^2\right)$$

Running time:
$$T(n) \in O\left(n + \sum_{i=1}^{n} n_i^2\right)$$

 n_i = the number of elements in B[i]

$$E[T(n)] \in O\left(n + \sum_{i=1}^{n} E[n_i]^2\right)$$

Running time:
$$T(n) \in O\left(n + \sum_{i=1}^{n} n_i^2\right)$$

 n_i = the number of elements in B[i]

$$\mathsf{E}[\mathsf{T}(\mathsf{n})] \in \mathsf{O}\left(\mathsf{n} + \sum_{\mathsf{i}=\mathsf{1}}^{\mathsf{n}} \mathsf{E}[\mathsf{n}_{\mathsf{i}}]^2\right)$$

Lemma: $E[n_i^2] < 2$.

Corollary: $E[T(n)] \in O(n)$.

Bucket Sort

Lemma: $E[n_i^2] < 2$.

$$X_j = \begin{cases} 1 & A[j] \text{ ends up in B[i]} \\ 0 & \text{otherwise} \end{cases}$$

$$X_j = \begin{cases} 1 & A[j] \text{ ends up in B[i]} \\ 0 & \text{otherwise} \end{cases}$$

$$n_i = \sum_{j=1}^n X_j$$

$$X_j = \begin{cases} 1 & A[j] \text{ ends up in B[i]} \\ 0 & \text{otherwise} \end{cases}$$

$$n_i = \sum_{j=1}^n X_j$$

$$E[n_i^2] = E\left[\left(\sum_{j=1}^n X_j\right)^2\right]$$

$$X_{j} = \begin{cases} 1 & A[j] \text{ ends up in B[i]} \\ 0 & \text{otherwise} \end{cases}$$

$$n_i = \sum_{j=1}^n X_j$$

$$E[n_i^2] = E\left[\left(\sum_{j=1}^n X_j\right)^2\right] = E\left[\sum_{j=1}^n \sum_{k=1}^n X_j X_k\right]$$

$$X_{j} = \begin{cases} 1 & A[j] \text{ ends up in B[i]} \\ 0 & \text{otherwise} \end{cases}$$

$$n_i = \sum_{j=1}^n X_j$$

$$\mathsf{E}[\mathsf{n}_\mathsf{i}^2] = \mathsf{E}\left[\left(\sum_{\mathsf{j}=\mathsf{I}}^\mathsf{n}\mathsf{X}_\mathsf{j}\right)^2\right] = \mathsf{E}\left[\sum_{\mathsf{j}=\mathsf{I}}^\mathsf{n}\sum_{\mathsf{k}=\mathsf{I}}^\mathsf{n}\mathsf{X}_\mathsf{j}\mathsf{X}_\mathsf{k}\right] = \sum_{\mathsf{j}=\mathsf{I}}^\mathsf{n}\sum_{\mathsf{k}=\mathsf{I}}^\mathsf{n}\mathsf{E}[\mathsf{X}_\mathsf{j}\mathsf{X}_\mathsf{k}]$$

$$X_j = \begin{cases} 1 & A[j] \text{ ends up in B[i]} \\ 0 & \text{otherwise} \end{cases}$$

$$n_i = \sum_{j=1}^n X_j$$

$$\begin{split} E[n_i^2] &= E\left[\left(\sum_{j=1}^n X_j\right)^2\right] = E\left[\sum_{j=1}^n \sum_{k=1}^n X_j X_k\right] = \sum_{j=1}^n \sum_{k=1}^n E[X_j X_k] \\ &= \sum_{j=1}^n E[X_j^2] + \sum_{j=1}^n \sum_{\substack{k=1 \\ k \neq j}}^n E[X_j] E[X_k] \end{split}$$

Lemma: $E[n_i^2] < 2$.

$$X_{j} = \begin{cases} 1 & A[j] \text{ ends up in B[i]} \\ 0 & \text{otherwise} \end{cases}$$

$$n_i = \sum_{j=1}^n X_j$$

$$\begin{split} E[n_i^2] &= E\left[\left(\sum_{j=1}^n X_j\right)^2\right] = E\left[\sum_{j=1}^n \sum_{k=1}^n X_j X_k\right] = \sum_{j=1}^n \sum_{k=1}^n E[X_j X_k] \\ &= \sum_{j=1}^n E[X_j^2] + \sum_{j=1}^n \sum_{\substack{k=1 \\ k \neq j}}^n E[X_j] E[X_k] \end{split}$$

 X_i and X_i are clearly not independent. X_i and X_k are independent.

$$E[X_j] = \frac{1}{n} \cdot 1 + \left(1 - \frac{1}{n}\right) \cdot 0 = \frac{1}{n}$$

$$E[X_j] = \frac{1}{n} \cdot 1 + \left(1 - \frac{1}{n}\right) \cdot 0 = \frac{1}{n}$$

$$E[X_j^2] = \frac{1}{n} \cdot I^2 + \left(1 - \frac{1}{n}\right) \cdot 0^2 = \frac{1}{n}$$

$$E[X_j] = \frac{1}{n} \cdot 1 + \left(1 - \frac{1}{n}\right) \cdot 0 = \frac{1}{n}$$

$$E[X_j^2] = \frac{1}{n} \cdot 1^2 + \left(1 - \frac{1}{n}\right) \cdot 0^2 = \frac{1}{n}$$

$$E[n_i^2] = \sum_{j=1}^n E[X_j^2] + \sum_{j=1}^n \sum_{\substack{k=1 \\ k \neq i}}^n E[X_j] E[X_k] = n \cdot \frac{1}{n} + \frac{n(n-1)}{n^2} < 2$$

For Quick Sort, we were able to eliminate assumptions about the input distribution using randomization.

For Quick Sort, we were able to eliminate assumptions about the input distribution using randomization.

Does that work for Bucket Sort?

For Quick Sort, we were able to eliminate assumptions about the input distribution using randomization.

Does that work for Bucket Sort?

No!

For Quick Sort, we were able to eliminate assumptions about the input distribution using randomization.

Does that work for Bucket Sort?

No!

For Quick Sort, we relied on a random ordering of the elements.

For Quick Sort, we were able to eliminate assumptions about the input distribution using randomization.

Does that work for Bucket Sort?

No!

For Quick Sort, we relied on a random ordering of the elements.

Randomly permuting the input to guarantee this does not affect the final result of the algorithm.

For Quick Sort, we were able to eliminate assumptions about the input distribution using randomization.

Does that work for Bucket Sort?

No!

For Quick Sort, we relied on a random ordering of the elements.

Randomly permuting the input to guarantee this does not affect the final result of the algorithm.

Bucket Sort relies on the random distribution of the input values.

For Quick Sort, we were able to eliminate assumptions about the input distribution using randomization.

Does that work for Bucket Sort?

No!

For Quick Sort, we relied on a random ordering of the elements.

Randomly permuting the input to guarantee this does not affect the final result of the algorithm.

Bucket Sort relies on the random distribution of the input values.

We can't simply change them without changing the algorithm's output.

Motwani/Raghavan.

Randomized Algorithms. Section 2.1.

Consider a game where two players, Max and Minnie, take turns. Assume the game cannot end in a draw.

Motwani/Raghavan.

Randomized Algorithms. Section 2.1.

Consider a game where two players, Max and Minnie, take turns. Assume the game cannot end in a draw.

We label a win for Max with I and a win for Minnie with 0.

Consider a game where two players, Max and Minnie, take turns. Assume the game cannot end in a draw.

We label a win for Max with I and a win for Minnie with 0.

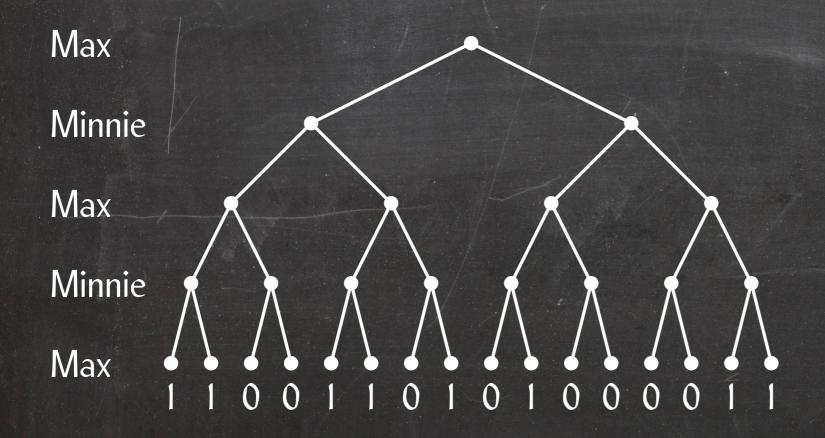
Max (Minnie) has a winning strategy if he can win the game no matter how Minnie (Max) plays.

Consider a game where two players, Max and Minnie, take turns. Assume the game cannot end in a draw.

We label a win for Max with I and a win for Minnie with 0.

Max (Minnie) has a winning strategy if he can win the game no matter how Minnie (Max) plays.

We can model all possible games as a game tree:

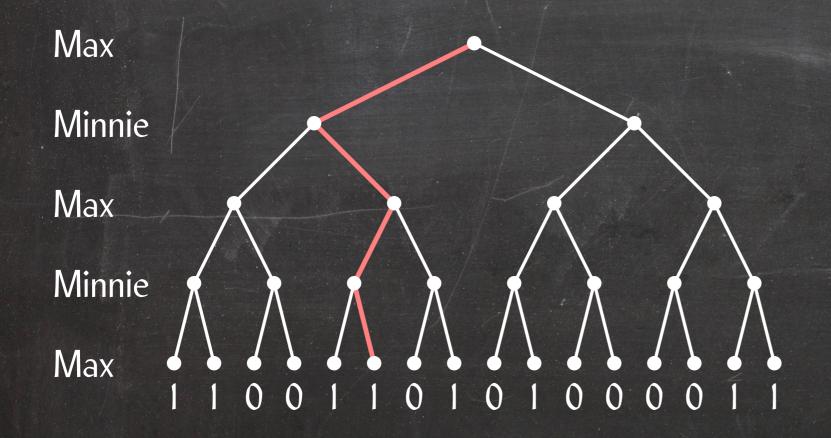


Consider a game where two players, Max and Minnie, take turns. Assume the game cannot end in a draw.

We label a win for Max with I and a win for Minnie with 0.

Max (Minnie) has a winning strategy if he can win the game no matter how Minnie (Max) plays.

We can model all possible games as a game tree:

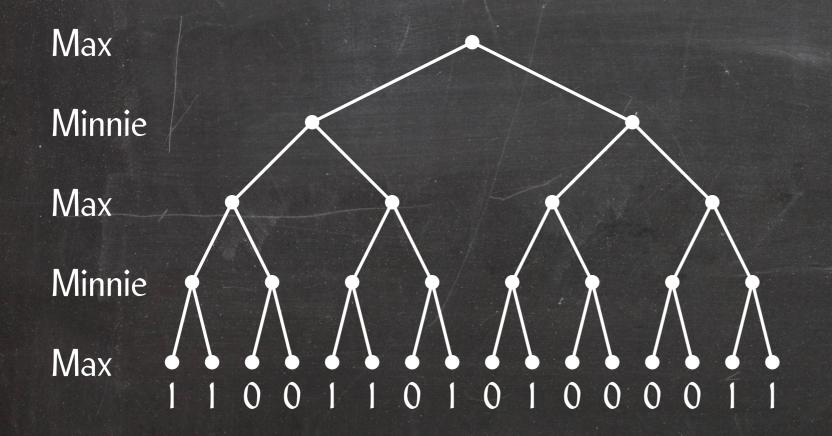


Consider a game where two players, Max and Minnie, take turns. Assume the game cannot end in a draw.

We label a win for Max with I and a win for Minnie with 0.

Max (Minnie) has a winning strategy if he can win the game no matter how Minnie (Max) plays.

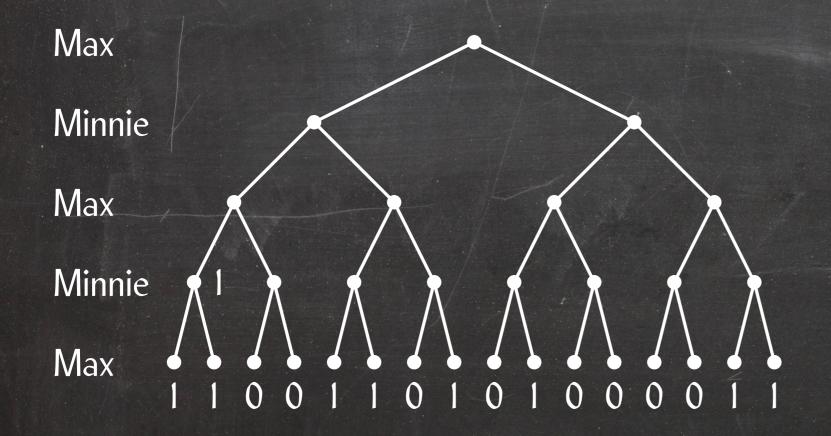
We can model all possible games as a game tree:



Consider a game where two players, Max and Minnie, take turns. Assume the game cannot end in a draw.

We label a win for Max with I and a win for Minnie with 0.

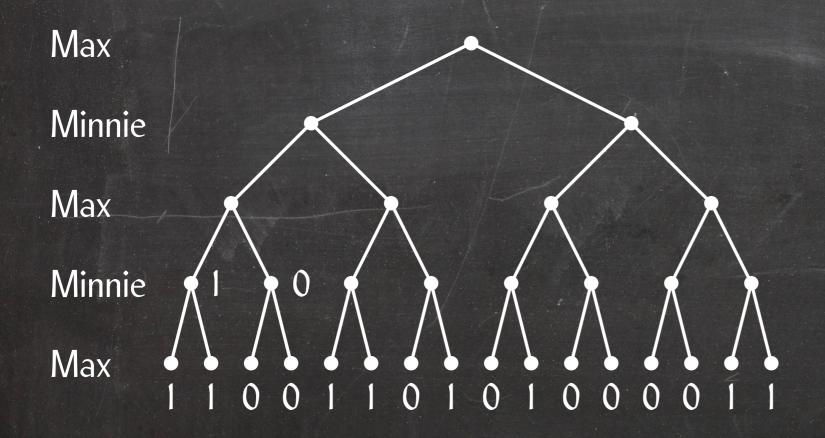
Max (Minnie) has a winning strategy if he can win the game no matter how Minnie (Max) plays.



Consider a game where two players, Max and Minnie, take turns. Assume the game cannot end in a draw.

We label a win for Max with I and a win for Minnie with 0.

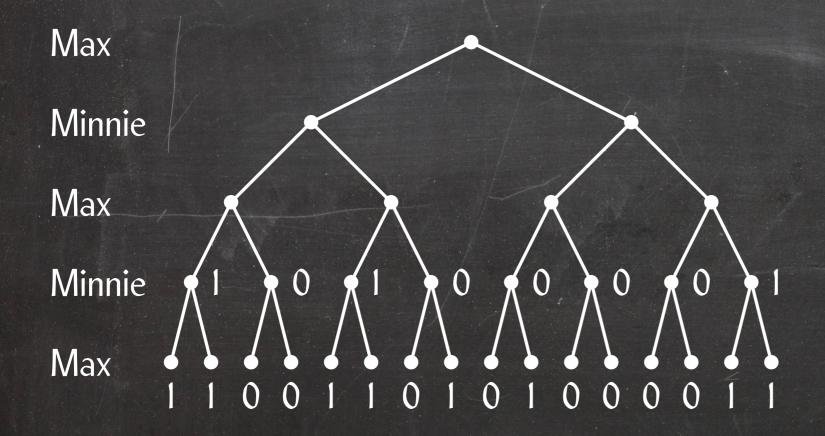
Max (Minnie) has a winning strategy if he can win the game no matter how Minnie (Max) plays.



Consider a game where two players, Max and Minnie, take turns. Assume the game cannot end in a draw.

We label a win for Max with I and a win for Minnie with 0.

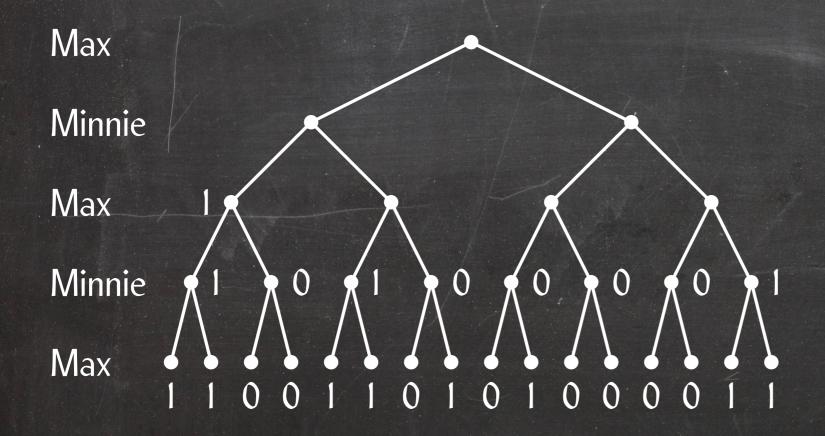
Max (Minnie) has a winning strategy if he can win the game no matter how Minnie (Max) plays.



Consider a game where two players, Max and Minnie, take turns. Assume the game cannot end in a draw.

We label a win for Max with I and a win for Minnie with 0.

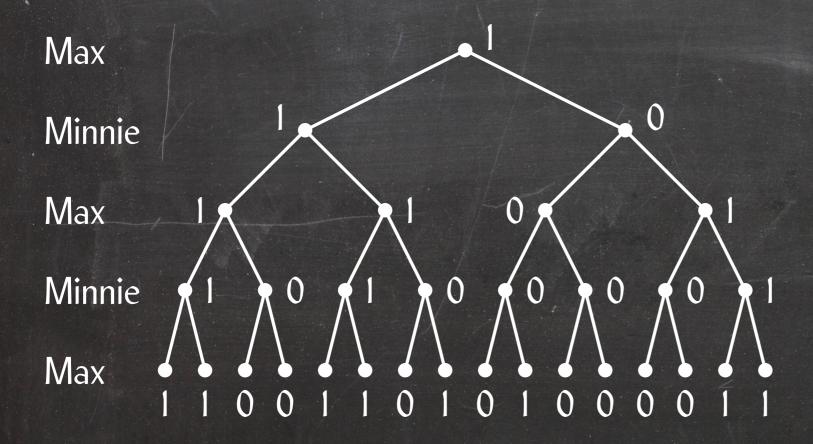
Max (Minnie) has a winning strategy if he can win the game no matter how Minnie (Max) plays.



Consider a game where two players, Max and Minnie, take turns. Assume the game cannot end in a draw.

We label a win for Max with I and a win for Minnie with 0.

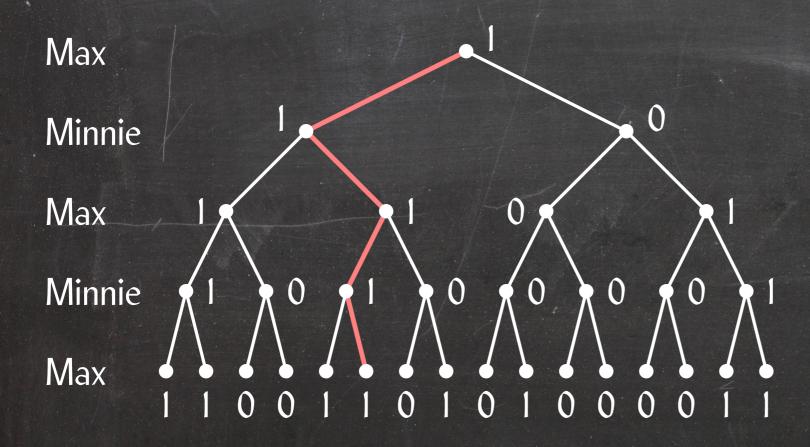
Max (Minnie) has a winning strategy if he can win the game no matter how Minnie (Max) plays.



Consider a game where two players, Max and Minnie, take turns. Assume the game cannot end in a draw.

We label a win for Max with I and a win for Minnie with 0.

Max (Minnie) has a winning strategy if he can win the game no matter how Minnie (Max) plays.

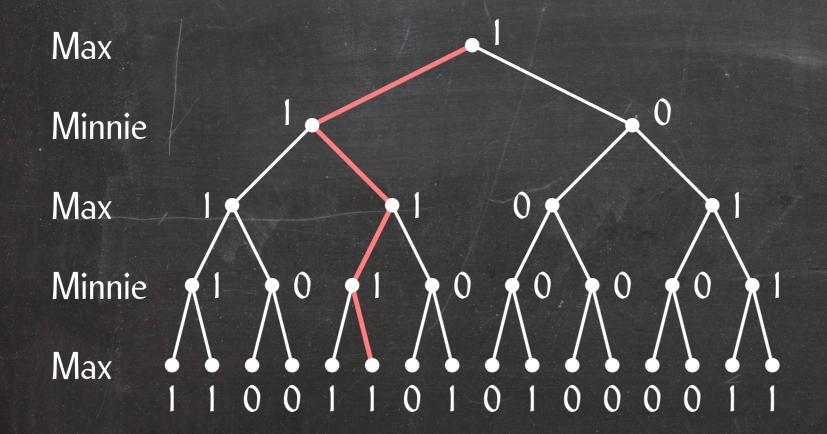


Consider a game where two players, Max and Minnie, take turns. Assume the game cannot end in a draw.

We label a win for Max with I and a win for Minnie with 0.

Max (Minnie) has a winning strategy if he can win the game no matter how Minnie (Max) plays.

We can model all possible games as a game tree:



Max-node:

 $label(v) = \max_{child \ w} label(w)$

Minnie-node:

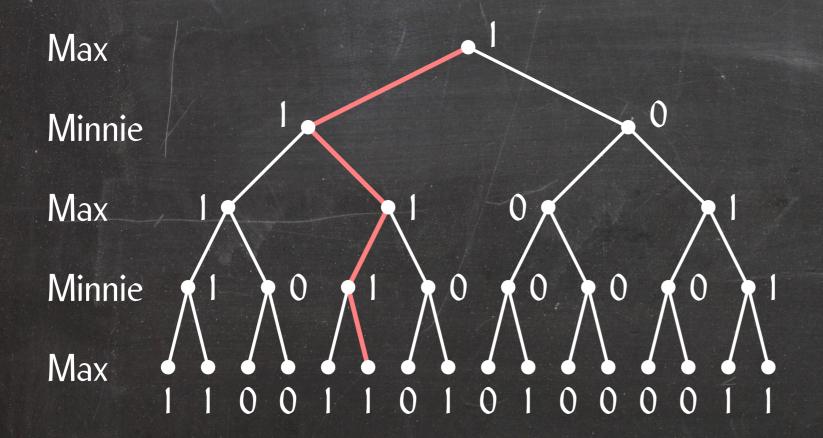
 $label(v) = \min_{child \ w} label(w)$

Consider a game where two players, Max and Minnie, take turns. Assume the game cannot end in a draw.

We label a win for Max with I and a win for Minnie with 0.

Max (Minnie) has a winning strategy if he can win the game no matter how Minnie (Max) plays.

We can model all possible games as a game tree:

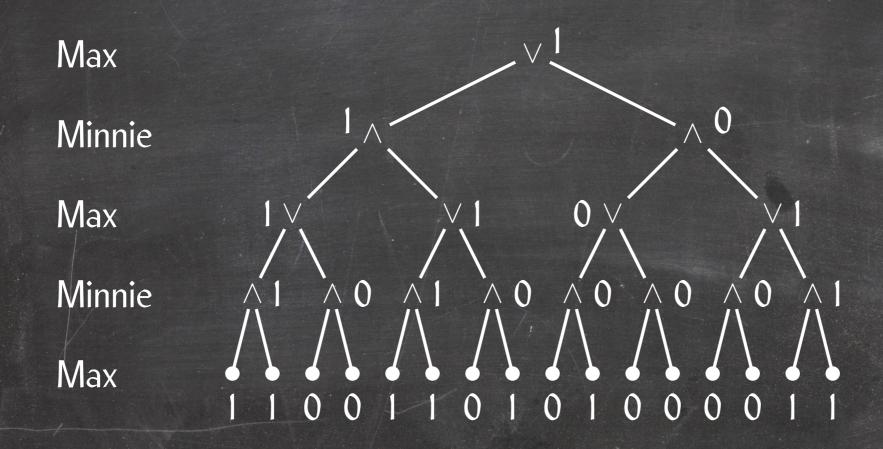


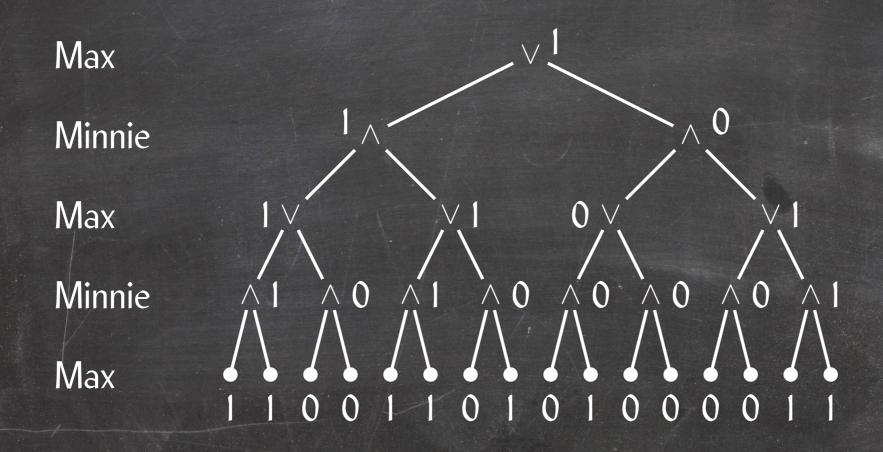
Max-node:

$$label(v) = \bigvee_{child w} label(w)$$

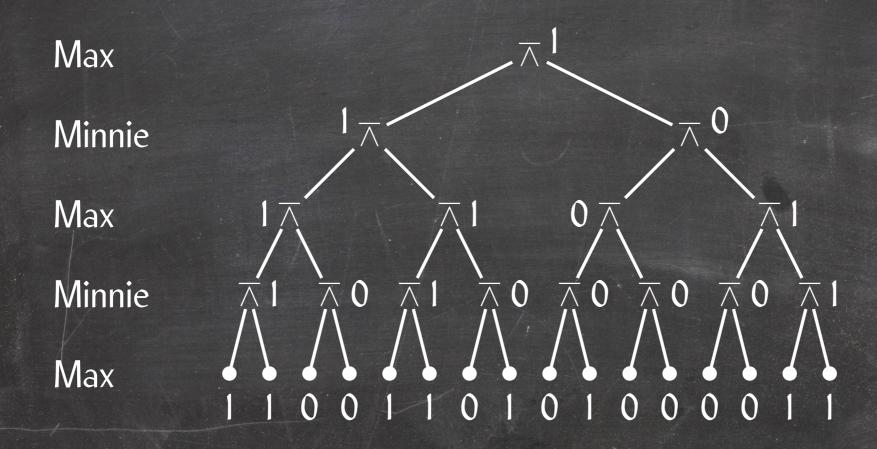
Minnie-node:

$$label(v) = \bigwedge_{child w} label(w)$$

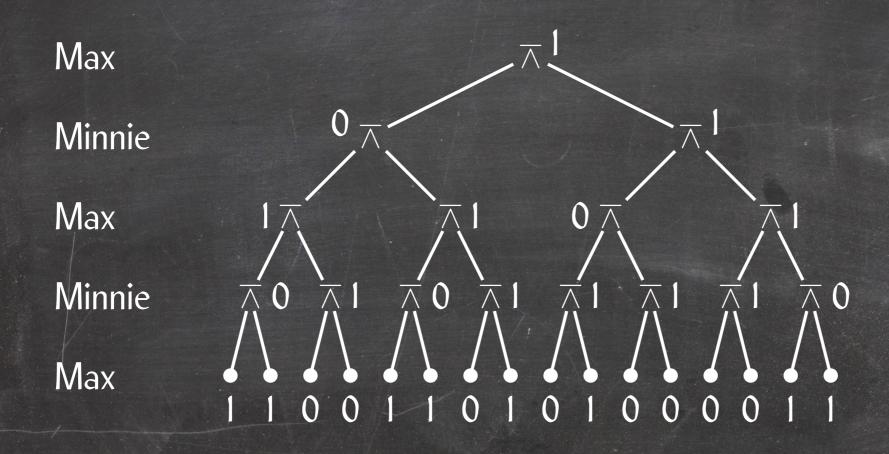




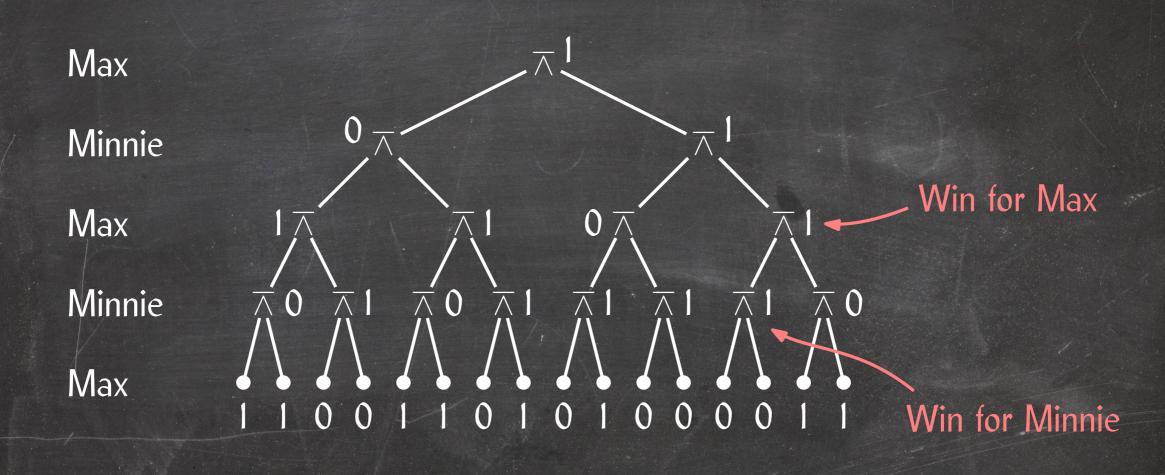
$$(a \land b) \lor (c \land d) = \overline{(a \land b)} \land \overline{c \land d}$$



$$(a \land b) \lor (c \land d) = \overline{(a \land b)} \land \overline{c \land d}$$



$$(a \land b) \lor (c \land d) = \overline{(a \land b)} \land \overline{c \land d}$$



$$(a \land b) \lor (c \land d) = \overline{(a \land b)} \land \overline{c \land d}$$

Game Tree Evaluation: A Deterministic Algorithm

GameValue(v)

- I if v is a leaf
- then return its value
- 3 else return not (GameValue(v.leftChild) and GameValue(v.rightChild))

Game Tree Evaluation: A Deterministic Algorithm

GameValue(v)

- I if v is a leaf
- then return its value
- 3 else return not (GameValue(v.leftChild) and GameValue(v.rightChild))

- One recursive call per node
- 2n − 1 nodes
- \Rightarrow Running time O(n)

Game Tree Evaluation: A Deterministic Algorithm

Game Value(v)

- I if v is a leaf
- then return its value
- 3 if not Game Value (v. left Child)
- 4 then return 1
- 5 else return not GameValue(v.rightChild)

- One recursive call per node
- 2n − 1 nodes
- \Rightarrow Running time O(n)

Observation: Any deterministic algorithm has to inspect every leaf in the worst case and thus take $\Omega(n)$ time in the worst case.

Observation: Any deterministic algorithm has to inspect every leaf in the worst case and thus take $\Omega(n)$ time in the worst case.

Adversary argument:

Observation: Any deterministic algorithm has to inspect every leaf in the worst case and thus take $\Omega(n)$ time in the worst case.

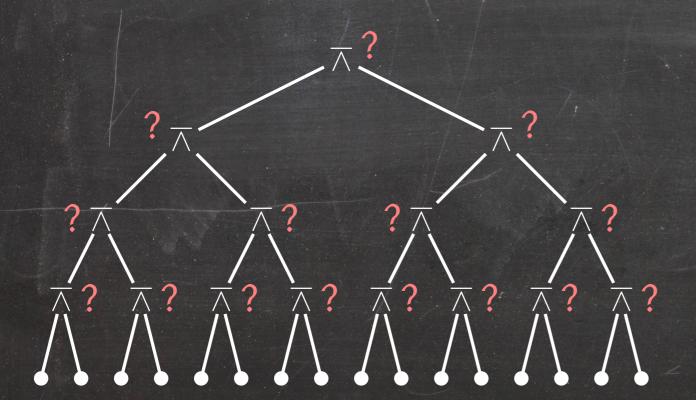
Adversary argument:

- Fix every input element the first time the algorithm inspects it.
- Choose this to ensure the algorithm runs as long as possible.

Observation: Any deterministic algorithm has to inspect every leaf in the worst case and thus take $\Omega(n)$ time in the worst case.

Adversary argument:

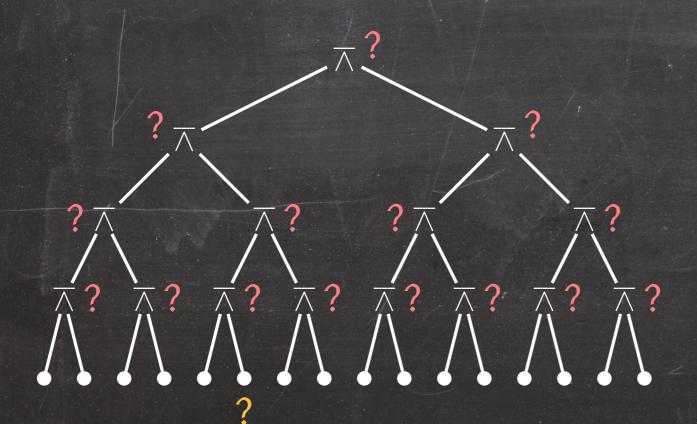
- Fix every input element the first time the algorithm inspects it.
- Choose this to ensure the algorithm runs as long as possible.



Observation: Any deterministic algorithm has to inspect every leaf in the worst case and thus take $\Omega(n)$ time in the worst case.

Adversary argument:

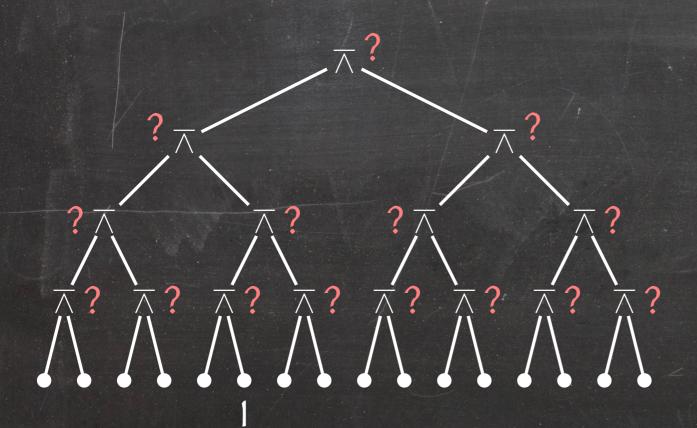
- Fix every input element the first time the algorithm inspects it.
- Choose this to ensure the algorithm runs as long as possible.



Observation: Any deterministic algorithm has to inspect every leaf in the worst case and thus take $\Omega(n)$ time in the worst case.

Adversary argument:

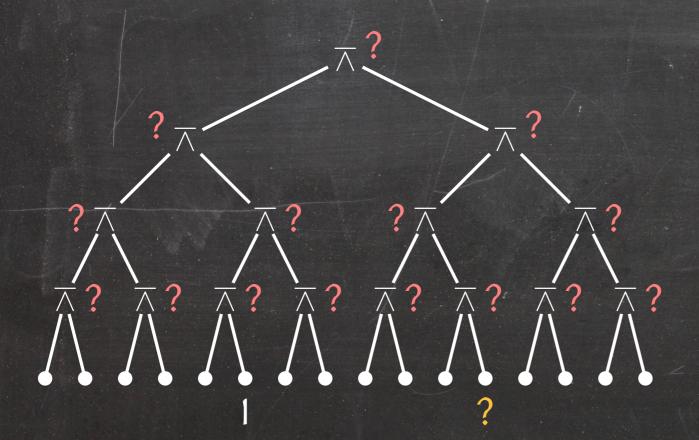
- Fix every input element the first time the algorithm inspects it.
- Choose this to ensure the algorithm runs as long as possible.



Observation: Any deterministic algorithm has to inspect every leaf in the worst case and thus take $\Omega(n)$ time in the worst case.

Adversary argument:

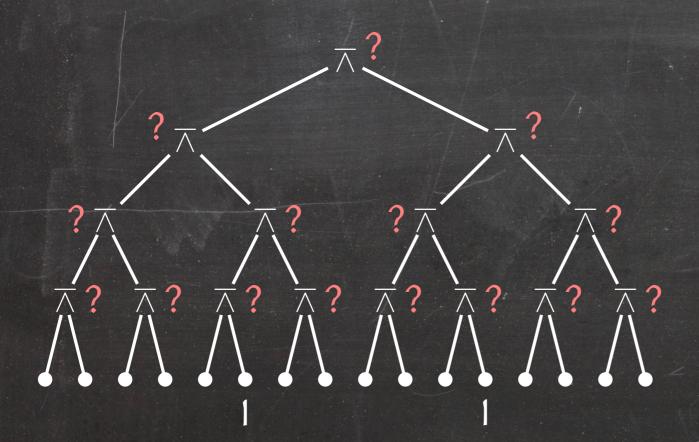
- Fix every input element the first time the algorithm inspects it.
- Choose this to ensure the algorithm runs as long as possible.



Observation: Any deterministic algorithm has to inspect every leaf in the worst case and thus take $\Omega(n)$ time in the worst case.

Adversary argument:

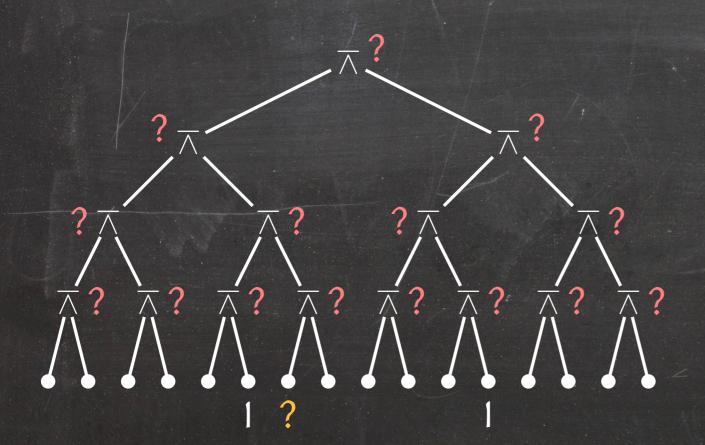
- Fix every input element the first time the algorithm inspects it.
- Choose this to ensure the algorithm runs as long as possible.



Observation: Any deterministic algorithm has to inspect every leaf in the worst case and thus take $\Omega(n)$ time in the worst case.

Adversary argument:

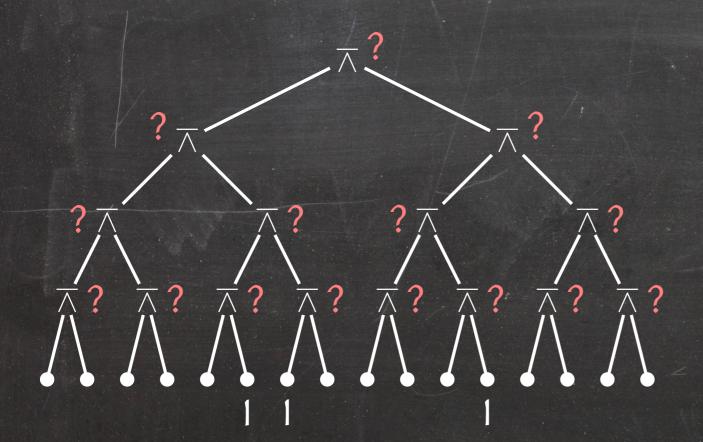
- Fix every input element the first time the algorithm inspects it.
- Choose this to ensure the algorithm runs as long as possible.



Observation: Any deterministic algorithm has to inspect every leaf in the worst case and thus take $\Omega(n)$ time in the worst case.

Adversary argument:

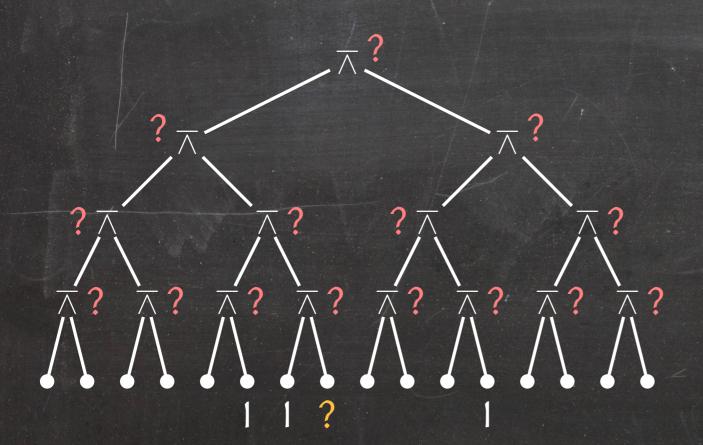
- Fix every input element the first time the algorithm inspects it.
- Choose this to ensure the algorithm runs as long as possible.



Observation: Any deterministic algorithm has to inspect every leaf in the worst case and thus take $\Omega(n)$ time in the worst case.

Adversary argument:

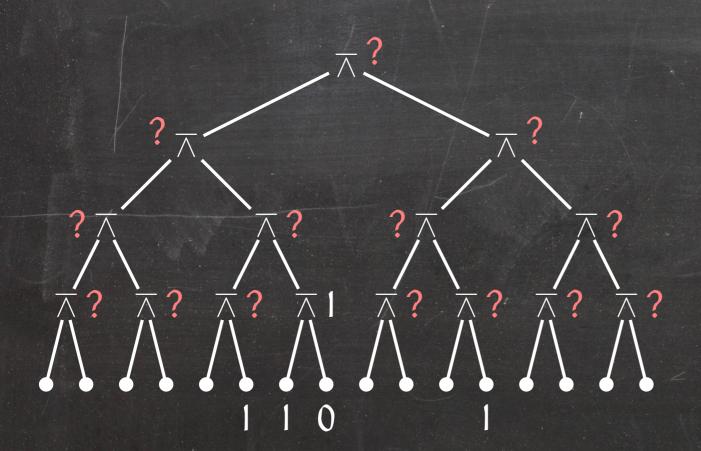
- Fix every input element the first time the algorithm inspects it.
- Choose this to ensure the algorithm runs as long as possible.



Observation: Any deterministic algorithm has to inspect every leaf in the worst case and thus take $\Omega(n)$ time in the worst case.

Adversary argument:

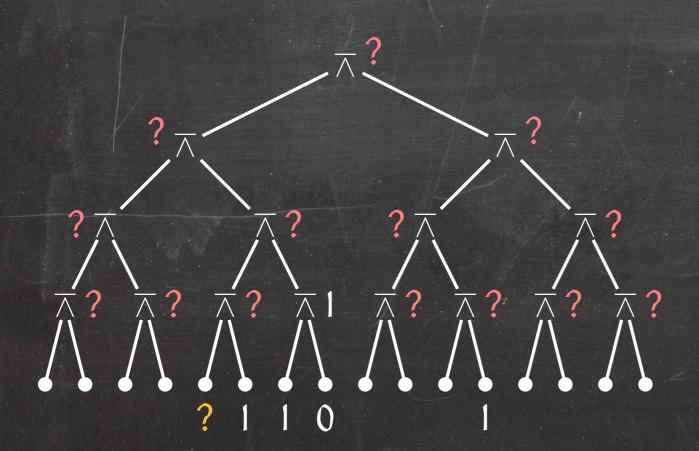
- Fix every input element the first time the algorithm inspects it.
- Choose this to ensure the algorithm runs as long as possible.



Observation: Any deterministic algorithm has to inspect every leaf in the worst case and thus take $\Omega(n)$ time in the worst case.

Adversary argument:

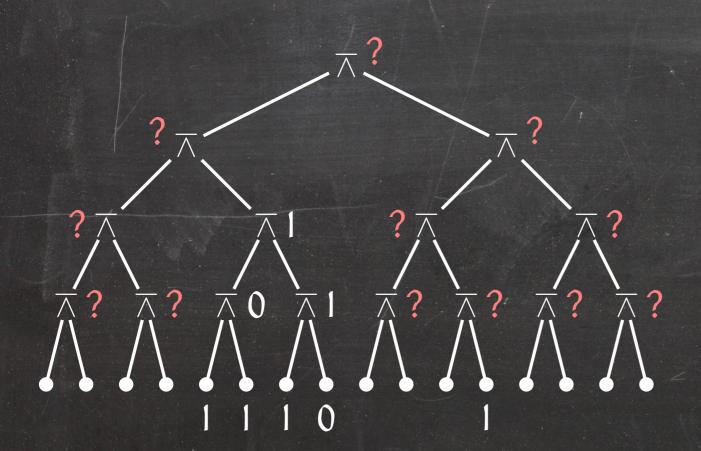
- Fix every input element the first time the algorithm inspects it.
- Choose this to ensure the algorithm runs as long as possible.



Observation: Any deterministic algorithm has to inspect every leaf in the worst case and thus take $\Omega(n)$ time in the worst case.

Adversary argument:

- Fix every input element the first time the algorithm inspects it.
- Choose this to ensure the algorithm runs as long as possible.

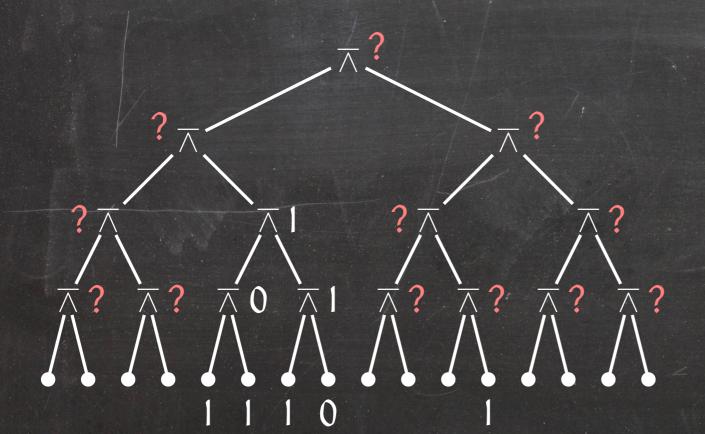


Observation: Any deterministic algorithm has to inspect every leaf in the worst case and thus take $\Omega(n)$ time in the worst case.

Adversary argument:

Can be used to construct a worst-case input for any deterministic algorithm, based on how the algorithm behaves.

- Fix every input element the first time the algorithm inspects it.
- Choose this to ensure the algorithm runs as long as possible.



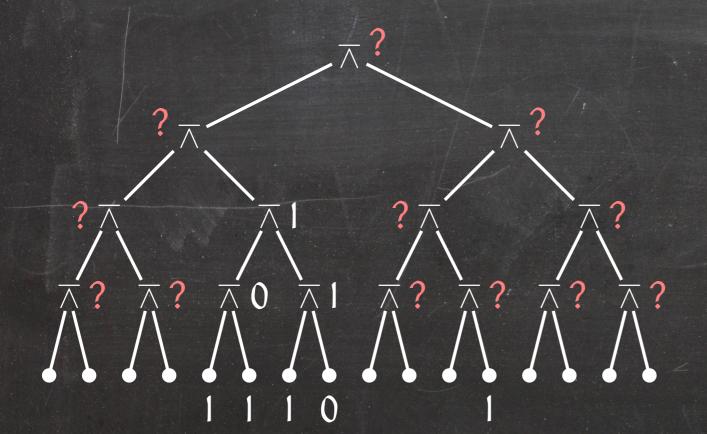
When a leaf is the last unknown leaf in a subtree, we cannot prevent the algorithm from learning the value of the root of the subtree.

Observation: Any deterministic algorithm has to inspect every leaf in the worst case and thus take $\Omega(n)$ time in the worst case.

Adversary argument:

Can be used to construct a worst-case input for any deterministic algorithm, based on how the algorithm behaves.

- Fix every input element the first time the algorithm inspects it.
- Choose this to ensure the algorithm runs as long as possible.



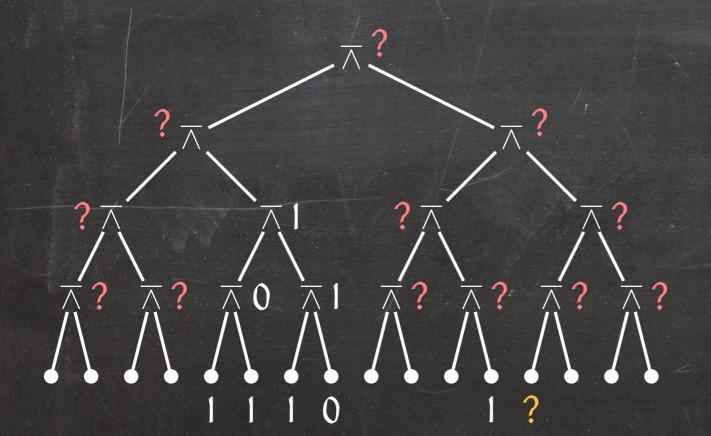
When a leaf is the last unknown leaf in a subtree, we cannot prevent the algorithm from learning the value of the root of the subtree.

Observation: Any deterministic algorithm has to inspect every leaf in the worst case and thus take $\Omega(n)$ time in the worst case.

Adversary argument:

Can be used to construct a worst-case input for any deterministic algorithm, based on how the algorithm behaves.

- Fix every input element the first time the algorithm inspects it.
- Choose this to ensure the algorithm runs as long as possible.



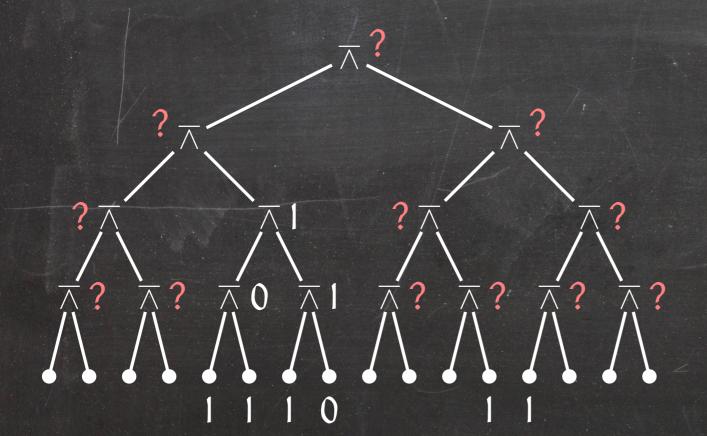
When a leaf is the last unknown leaf in a subtree, we cannot prevent the algorithm from learning the value of the root of the subtree.

Observation: Any deterministic algorithm has to inspect every leaf in the worst case and thus take $\Omega(n)$ time in the worst case.

Adversary argument:

Can be used to construct a worst-case input for any deterministic algorithm, based on how the algorithm behaves.

- Fix every input element the first time the algorithm inspects it.
- Choose this to ensure the algorithm runs as long as possible.



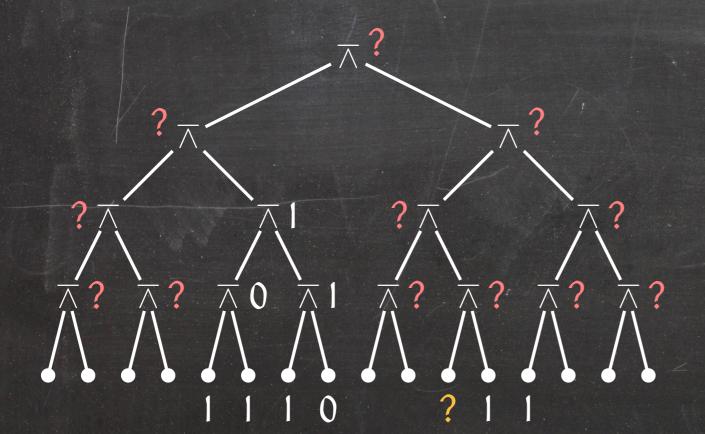
When a leaf is the last unknown leaf in a subtree, we cannot prevent the algorithm from learning the value of the root of the subtree.

Observation: Any deterministic algorithm has to inspect every leaf in the worst case and thus take $\Omega(n)$ time in the worst case.

Adversary argument:

Can be used to construct a worst-case input for any deterministic algorithm, based on how the algorithm behaves.

- Fix every input element the first time the algorithm inspects it.
- Choose this to ensure the algorithm runs as long as possible.



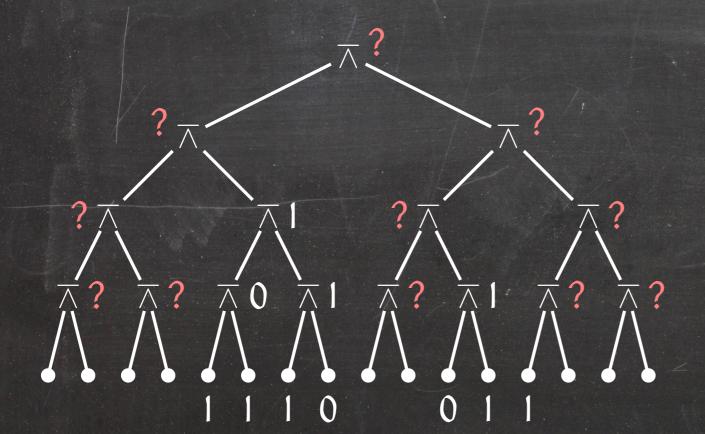
When a leaf is the last unknown leaf in a subtree, we cannot prevent the algorithm from learning the value of the root of the subtree.

Observation: Any deterministic algorithm has to inspect every leaf in the worst case and thus take $\Omega(n)$ time in the worst case.

Adversary argument:

Can be used to construct a worst-case input for any deterministic algorithm, based on how the algorithm behaves.

- Fix every input element the first time the algorithm inspects it.
- Choose this to ensure the algorithm runs as long as possible.



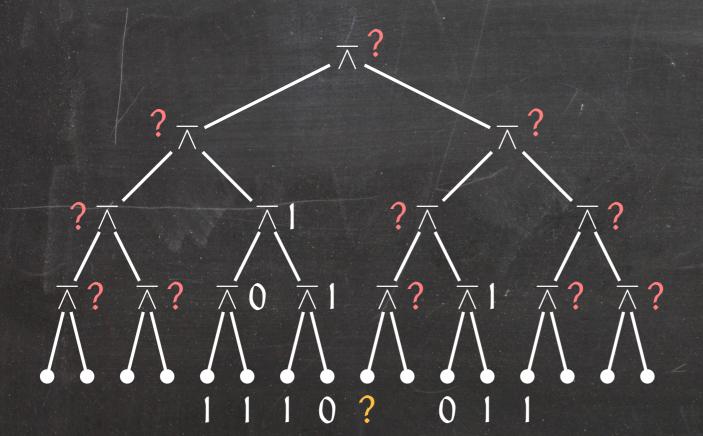
When a leaf is the last unknown leaf in a subtree, we cannot prevent the algorithm from learning the value of the root of the subtree.

Observation: Any deterministic algorithm has to inspect every leaf in the worst case and thus take $\Omega(n)$ time in the worst case.

Adversary argument:

Can be used to construct a worst-case input for any deterministic algorithm, based on how the algorithm behaves.

- Fix every input element the first time the algorithm inspects it.
- Choose this to ensure the algorithm runs as long as possible.



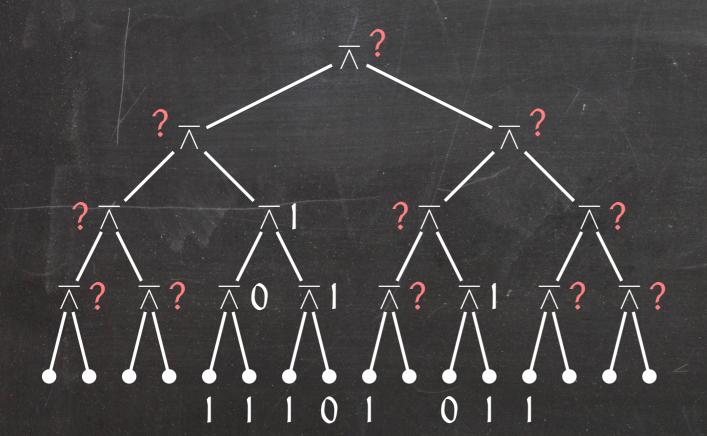
When a leaf is the last unknown leaf in a subtree, we cannot prevent the algorithm from learning the value of the root of the subtree.

Observation: Any deterministic algorithm has to inspect every leaf in the worst case and thus take $\Omega(n)$ time in the worst case.

Adversary argument:

Can be used to construct a worst-case input for any deterministic algorithm, based on how the algorithm behaves.

- Fix every input element the first time the algorithm inspects it.
- Choose this to ensure the algorithm runs as long as possible.



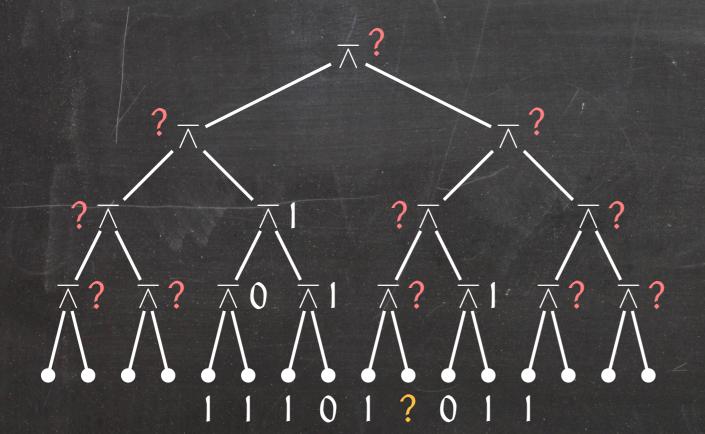
When a leaf is the last unknown leaf in a subtree, we cannot prevent the algorithm from learning the value of the root of the subtree.

Observation: Any deterministic algorithm has to inspect every leaf in the worst case and thus take $\Omega(n)$ time in the worst case.

Adversary argument:

Can be used to construct a worst-case input for any deterministic algorithm, based on how the algorithm behaves.

- Fix every input element the first time the algorithm inspects it.
- Choose this to ensure the algorithm runs as long as possible.



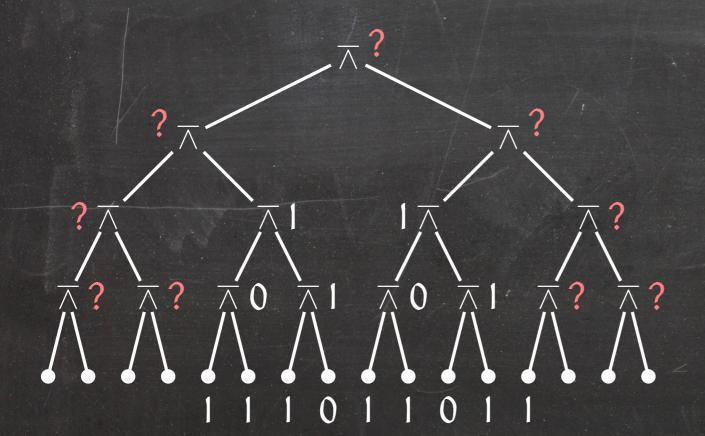
When a leaf is the last unknown leaf in a subtree, we cannot prevent the algorithm from learning the value of the root of the subtree.

Observation: Any deterministic algorithm has to inspect every leaf in the worst case and thus take $\Omega(n)$ time in the worst case.

Adversary argument:

Can be used to construct a worst-case input for any deterministic algorithm, based on how the algorithm behaves.

- Fix every input element the first time the algorithm inspects it.
- Choose this to ensure the algorithm runs as long as possible.



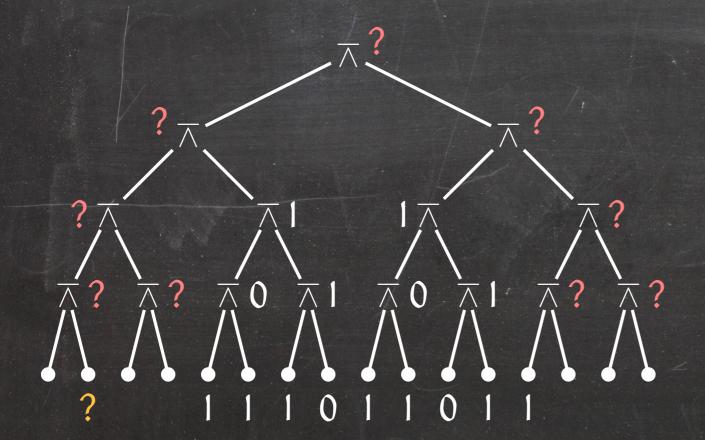
When a leaf is the last unknown leaf in a subtree, we cannot prevent the algorithm from learning the value of the root of the subtree.

Observation: Any deterministic algorithm has to inspect every leaf in the worst case and thus take $\Omega(n)$ time in the worst case.

Adversary argument:

Can be used to construct a worst-case input for any deterministic algorithm, based on how the algorithm behaves.

- Fix every input element the first time the algorithm inspects it.
- Choose this to ensure the algorithm runs as long as possible.



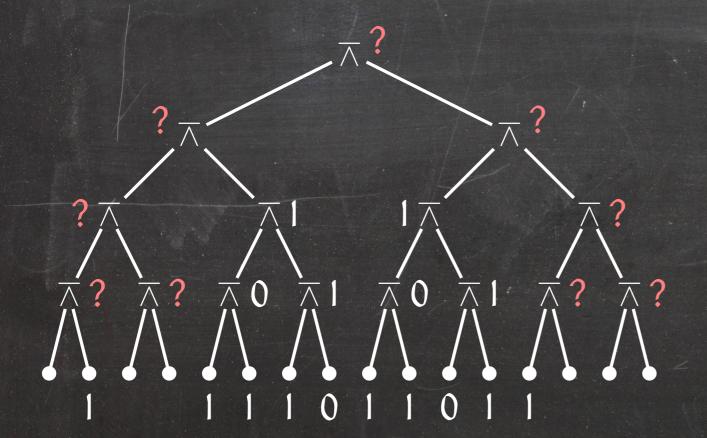
When a leaf is the last unknown leaf in a subtree, we cannot prevent the algorithm from learning the value of the root of the subtree.

Observation: Any deterministic algorithm has to inspect every leaf in the worst case and thus take $\Omega(n)$ time in the worst case.

Adversary argument:

Can be used to construct a worst-case input for any deterministic algorithm, based on how the algorithm behaves.

- Fix every input element the first time the algorithm inspects it.
- Choose this to ensure the algorithm runs as long as possible.



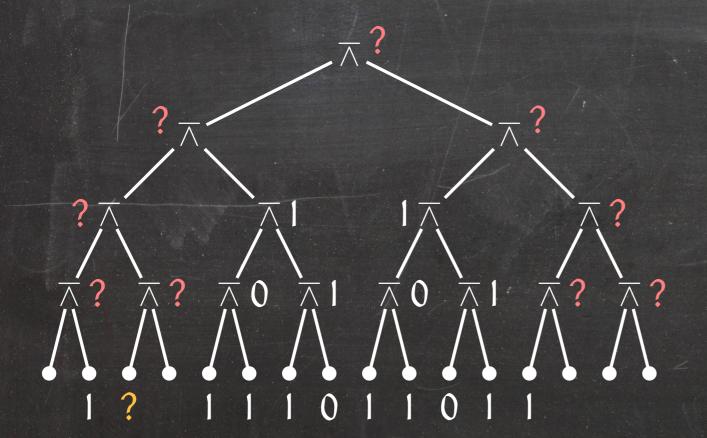
When a leaf is the last unknown leaf in a subtree, we cannot prevent the algorithm from learning the value of the root of the subtree.

Observation: Any deterministic algorithm has to inspect every leaf in the worst case and thus take $\Omega(n)$ time in the worst case.

Adversary argument:

Can be used to construct a worst-case input for any deterministic algorithm, based on how the algorithm behaves.

- Fix every input element the first time the algorithm inspects it.
- Choose this to ensure the algorithm runs as long as possible.



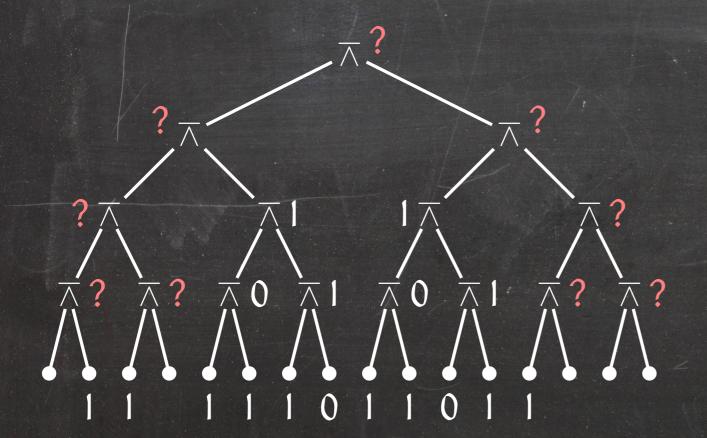
When a leaf is the last unknown leaf in a subtree, we cannot prevent the algorithm from learning the value of the root of the subtree.

Observation: Any deterministic algorithm has to inspect every leaf in the worst case and thus take $\Omega(n)$ time in the worst case.

Adversary argument:

Can be used to construct a worst-case input for any deterministic algorithm, based on how the algorithm behaves.

- Fix every input element the first time the algorithm inspects it.
- Choose this to ensure the algorithm runs as long as possible.



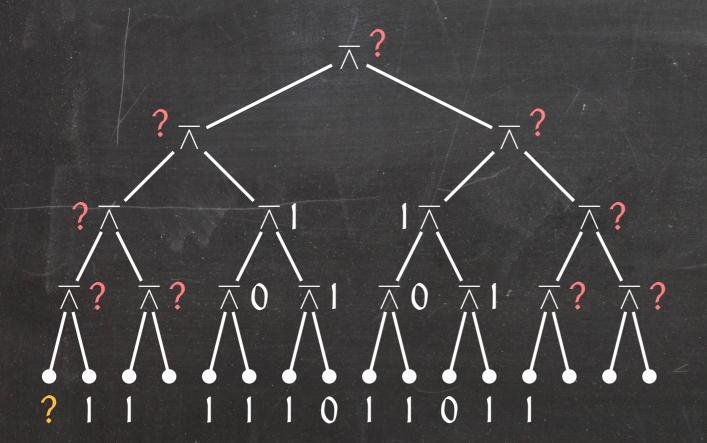
When a leaf is the last unknown leaf in a subtree, we cannot prevent the algorithm from learning the value of the root of the subtree.

Observation: Any deterministic algorithm has to inspect every leaf in the worst case and thus take $\Omega(n)$ time in the worst case.

Adversary argument:

Can be used to construct a worst-case input for any deterministic algorithm, based on how the algorithm behaves.

- Fix every input element the first time the algorithm inspects it.
- Choose this to ensure the algorithm runs as long as possible.



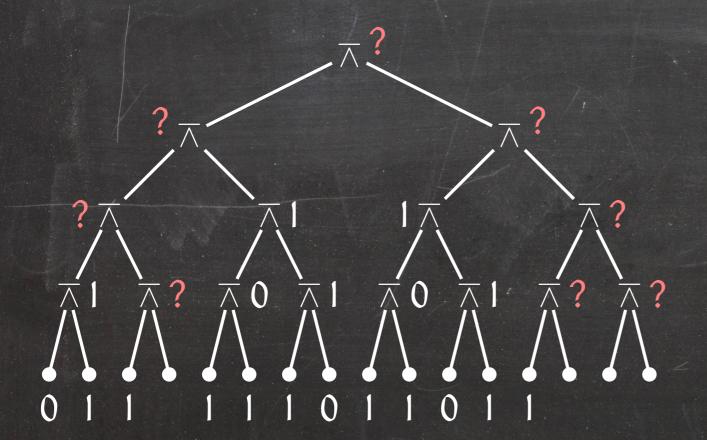
When a leaf is the last unknown leaf in a subtree, we cannot prevent the algorithm from learning the value of the root of the subtree.

Observation: Any deterministic algorithm has to inspect every leaf in the worst case and thus take $\Omega(n)$ time in the worst case.

Adversary argument:

Can be used to construct a worst-case input for any deterministic algorithm, based on how the algorithm behaves.

- Fix every input element the first time the algorithm inspects it.
- Choose this to ensure the algorithm runs as long as possible.



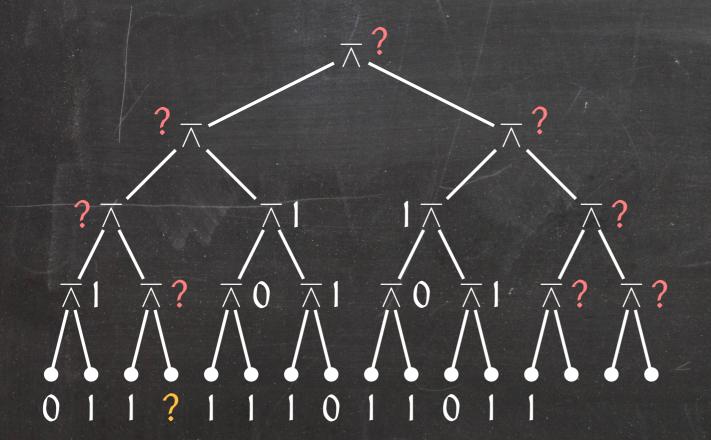
When a leaf is the last unknown leaf in a subtree, we cannot prevent the algorithm from learning the value of the root of the subtree.

Observation: Any deterministic algorithm has to inspect every leaf in the worst case and thus take $\Omega(n)$ time in the worst case.

Adversary argument:

Can be used to construct a worst-case input for any deterministic algorithm, based on how the algorithm behaves.

- Fix every input element the first time the algorithm inspects it.
- Choose this to ensure the algorithm runs as long as possible.



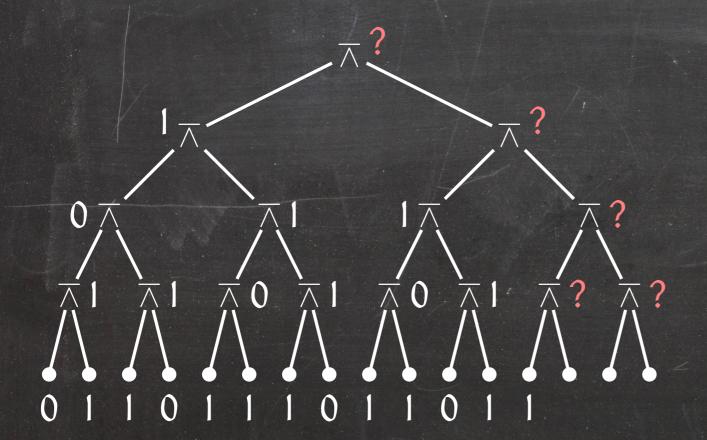
When a leaf is the last unknown leaf in a subtree, we cannot prevent the algorithm from learning the value of the root of the subtree.

Observation: Any deterministic algorithm has to inspect every leaf in the worst case and thus take $\Omega(n)$ time in the worst case.

Adversary argument:

Can be used to construct a worst-case input for any deterministic algorithm, based on how the algorithm behaves.

- Fix every input element the first time the algorithm inspects it.
- Choose this to ensure the algorithm runs as long as possible.



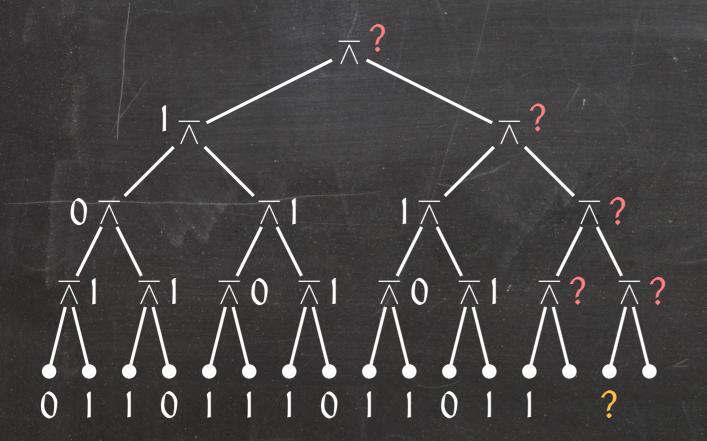
When a leaf is the last unknown leaf in a subtree, we cannot prevent the algorithm from learning the value of the root of the subtree.

Observation: Any deterministic algorithm has to inspect every leaf in the worst case and thus take $\Omega(n)$ time in the worst case.

Adversary argument:

Can be used to construct a worst-case input for any deterministic algorithm, based on how the algorithm behaves.

- Fix every input element the first time the algorithm inspects it.
- Choose this to ensure the algorithm runs as long as possible.



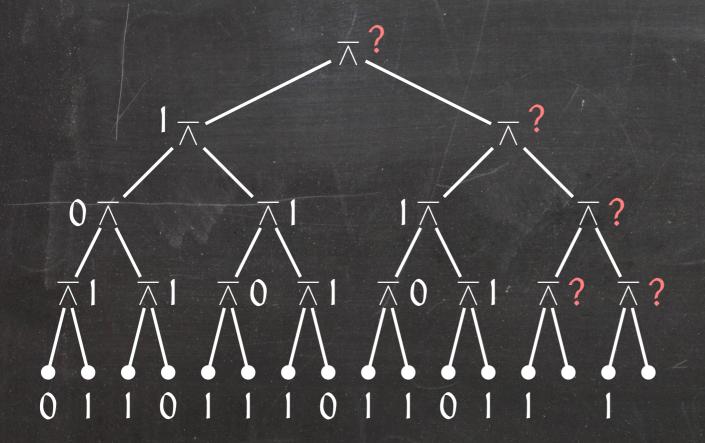
When a leaf is the last unknown leaf in a subtree, we cannot prevent the algorithm from learning the value of the root of the subtree.

Observation: Any deterministic algorithm has to inspect every leaf in the worst case and thus take $\Omega(n)$ time in the worst case.

Adversary argument:

Can be used to construct a worst-case input for any deterministic algorithm, based on how the algorithm behaves.

- Fix every input element the first time the algorithm inspects it.
- Choose this to ensure the algorithm runs as long as possible.



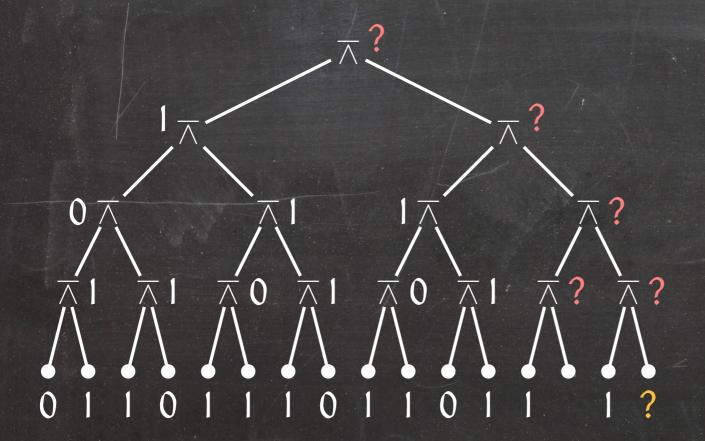
When a leaf is the last unknown leaf in a subtree, we cannot prevent the algorithm from learning the value of the root of the subtree.

Observation: Any deterministic algorithm has to inspect every leaf in the worst case and thus take $\Omega(n)$ time in the worst case.

Adversary argument:

Can be used to construct a worst-case input for any deterministic algorithm, based on how the algorithm behaves.

- Fix every input element the first time the algorithm inspects it.
- Choose this to ensure the algorithm runs as long as possible.



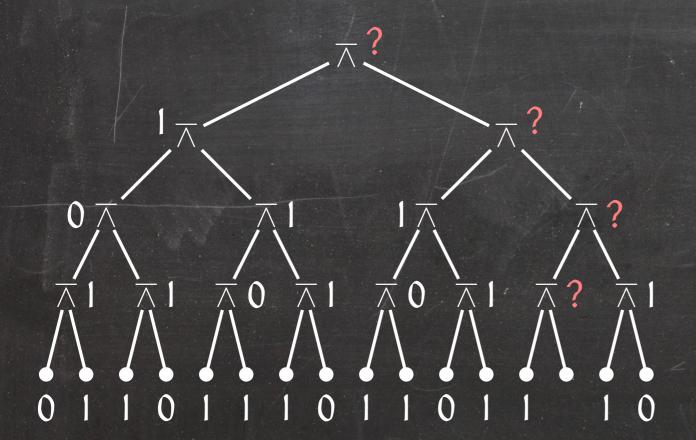
When a leaf is the last unknown leaf in a subtree, we cannot prevent the algorithm from learning the value of the root of the subtree.

Observation: Any deterministic algorithm has to inspect every leaf in the worst case and thus take $\Omega(n)$ time in the worst case.

Adversary argument:

Can be used to construct a worst-case input for any deterministic algorithm, based on how the algorithm behaves.

- Fix every input element the first time the algorithm inspects it.
- Choose this to ensure the algorithm runs as long as possible.



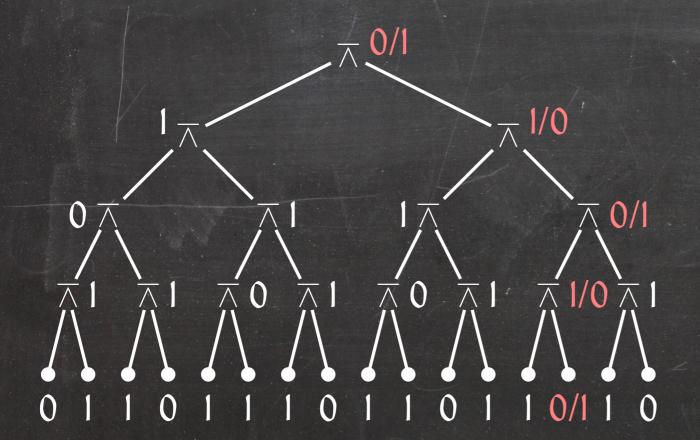
When a leaf is the last unknown leaf in a subtree, we cannot prevent the algorithm from learning the value of the root of the subtree.

Observation: Any deterministic algorithm has to inspect every leaf in the worst case and thus take $\Omega(n)$ time in the worst case.

Adversary argument:

Can be used to construct a worst-case input for any deterministic algorithm, based on how the algorithm behaves.

- Fix every input element the first time the algorithm inspects it.
- Choose this to ensure the algorithm runs as long as possible.



When a leaf is the last unknown leaf in a subtree, we cannot prevent the algorithm from learning the value of the root of the subtree.

RandomizedGameValue(v)

```
if v is a leaf
       then return its value
    coinFlip = RandomNumber(0,1)
    if coinFlip = 1
5
       then first = v.leftChild
            second = v.rightChild
6
      else first = v.rightChild
            second = v.leftChild
8
    if not f = GameValue(first)
9
       then return 1
10
       else return not GameValue(second)
```

RandomizedGameValue(v)

```
if v is a leaf
       then return its value
    coinFlip = RandomNumber(0,1)
    if coinFlip = 1
5
       then first = v.leftChild
6
            second = v.rightChild
       else first = v.rightChild
            second = v.leftChild
8
    if not f = GameValue(first)
9
       then return 1
10
       else return not GameValue(second)
11
```

Lemma: The expected running time of RandomizedGameValue on any input is in $O(n^{0.754})$.

 $E_i[T(n)] =$ expected running time on n leaves if the result is i $(i \in \{0, 1\})$

$$E_i[T(n)] =$$
expected running time on n leaves if the result is i $(i \in \{0, 1\})$

$$E_0[T(n)] = 2 \cdot E_1 \left[T \left(\frac{n}{2} \right) \right] + O(1)$$

$$E_i[T(n)] =$$
expected running time on n leaves if the result is i $(i \in \{0,1\})$

$$E_0[T(n)] = 2 \cdot E_1 \left[T \left(\frac{n}{2} \right) \right] + O(1)$$

$$E_1[T(n)] \leq \frac{1}{2} \cdot E_0\left[T\left(\frac{n}{2}\right)\right] + \frac{1}{2} \cdot \left(E_1\left[T\left(\frac{n}{2}\right)\right] + E_0\left[T\left(\frac{n}{2}\right)\right]\right) + O(1)$$

$$E_i[T(n)] =$$
expected running time on n leaves if the result is i $(i \in \{0,1\})$

$$E_0[T(n)] = 2 \cdot E_1 \left[T \left(\frac{n}{2} \right) \right] + O(1)$$

$$\begin{split} E_{I}[T(n)] &\leq \frac{1}{2} \cdot E_{0} \left[T \left(\frac{n}{2} \right) \right] + \frac{1}{2} \cdot \left(E_{I} \left[T \left(\frac{n}{2} \right) \right] + E_{0} \left[T \left(\frac{n}{2} \right) \right] \right) + O(I) \\ &= E_{0} \left[T \left(\frac{n}{2} \right) \right] + \frac{1}{2} \cdot E_{I} \left[T \left(\frac{n}{2} \right) \right] + O(I) \end{split}$$

$$E_i[T(n)] =$$
expected running time on n leaves if the result is i $(i \in \{0,1\})$

$$E_0[T(n)] = 2 \cdot E_1 \left[T\left(\frac{n}{2}\right)\right] + O(1)$$

$$\begin{split} E_{1}[T(n)] &\leq \frac{1}{2} \cdot E_{0} \left[T \left(\frac{n}{2} \right) \right] + \frac{1}{2} \cdot \left(E_{1} \left[T \left(\frac{n}{2} \right) \right] + E_{0} \left[T \left(\frac{n}{2} \right) \right] \right) + O(I) \\ &= E_{0} \left[T \left(\frac{n}{2} \right) \right] + \frac{1}{2} \cdot E_{1} \left[T \left(\frac{n}{2} \right) \right] + O(I) \\ &= 2 \cdot E_{1} \left[T \left(\frac{n}{4} \right) \right] + \frac{1}{2} \cdot E_{1} \left[T \left(\frac{n}{2} \right) \right] + O(I) \end{split}$$

$$E_i[T(n)] = expected running time on n leaves if the result is i (i $\in \{0, 1\}$)$$

$$E_0[T(n)] = 2 \cdot E_1 \left[T \left(\frac{n}{2} \right) \right] + O(1)$$

$$\begin{split} E_{1}[T(n)] &\leq \frac{1}{2} \cdot E_{0} \left[T \left(\frac{n}{2} \right) \right] + \frac{1}{2} \cdot \left(E_{1} \left[T \left(\frac{n}{2} \right) \right] + E_{0} \left[T \left(\frac{n}{2} \right) \right] \right) + O(I) \\ &= E_{0} \left[T \left(\frac{n}{2} \right) \right] + \frac{1}{2} \cdot E_{1} \left[T \left(\frac{n}{2} \right) \right] + O(I) \\ &= 2 \cdot E_{1} \left[T \left(\frac{n}{4} \right) \right] + \frac{1}{2} \cdot E_{1} \left[T \left(\frac{n}{2} \right) \right] + O(I) \end{split}$$

$$E[T(n)] \leq \max\left(2 \cdot E_1\left[T\left(\frac{n}{2}\right)\right], E_1[T(n)]\right)$$

Lemma: The expected running time of RandomizedGameValue on any input is in O(n^{0.754}).

 $E_i[T(n)] =$ expected running time on n leaves if the result is i $(i \in \{0, 1\})$

$$E_0[T(n)] = 2 \cdot E_1 \left[T \left(\frac{n}{2} \right) \right] + O(1)$$

$$\begin{split} E_{I}[T(n)] &\leq \frac{1}{2} \cdot E_{0} \left[T \left(\frac{n}{2} \right) \right] + \frac{1}{2} \cdot \left(E_{I} \left[T \left(\frac{n}{2} \right) \right] + E_{0} \left[T \left(\frac{n}{2} \right) \right] \right) + O(I) \\ &= E_{0} \left[T \left(\frac{n}{2} \right) \right] + \frac{1}{2} \cdot E_{I} \left[T \left(\frac{n}{2} \right) \right] + O(I) \\ &= 2 \cdot E_{I} \left[T \left(\frac{n}{4} \right) \right] + \frac{1}{2} \cdot E_{I} \left[T \left(\frac{n}{2} \right) \right] + O(I) \end{split}$$

$$E[T(n)] \leq \max\left(2 \cdot E_1\left[T\left(\frac{n}{2}\right)\right], E_1[T(n)]\right)$$

$$E_1[T(n)] \in O(n^{0.754}) \Rightarrow E[T(n)] \in O(n^{0.754})$$

Claim: $E_1[T(n)] \le cn^{\alpha} - d$ for some c > d > 0 and all $n \ge 1$, where $\alpha = lg\left(\frac{1+\sqrt{33}}{4}\right) \le 0.754$.

Claim: $E_1[T(n)] \le cn^{\alpha} - d$ for some c > d > 0 and all $n \ge 1$, where $\alpha = \lg\left(\frac{1+\sqrt{33}}{4}\right) \le 0.754$.

Base case: $1 \le n < 2$.

 $T(n) \in O(I) \Rightarrow E_I[T(n)] \le cn^{\alpha} - d$ for any d and c sufficiently larger than d.

Claim: $E_1[T(n)] \le cn^{\alpha} - d$ for some c > d > 0 and all $n \ge 1$, where $\alpha = \lg\left(\frac{1+\sqrt{33}}{4}\right) \le 0.754$.

$$\mathsf{E_1}[\mathsf{T}(\mathsf{n})] \leq 2 \cdot \mathsf{E_1}\left[\mathsf{T}\left(\frac{\mathsf{n}}{4}\right)\right] + \frac{1}{2} \cdot \mathsf{E_1}\left[\mathsf{T}\left(\frac{\mathsf{n}}{2}\right)\right] + \mathsf{a}$$

Claim: $E_1[T(n)] \le cn^{\alpha} - d$ for some c > d > 0 and all $n \ge 1$, where $\alpha = lg\left(\frac{1+\sqrt{33}}{4}\right) \le 0.754$.

$$\begin{split} E_{l}[T(n)] &\leq 2 \cdot E_{l} \left[T \left(\frac{n}{4} \right) \right] + \frac{1}{2} \cdot E_{l} \left[T \left(\frac{n}{2} \right) \right] + a \\ &\leq 2 \cdot \left[c \left(\frac{n}{4} \right)^{\alpha} - d \right] + \frac{1}{2} \cdot \left[\left(\frac{n}{2} \right)^{\alpha} - d \right] + a \end{split}$$

Claim: $E_1[T(n)] \le cn^{\alpha} - d$ for some c > d > 0 and all $n \ge 1$, where $\alpha = lg\left(\frac{1+\sqrt{33}}{4}\right) \le 0.754$.

$$\begin{split} E_1[T(n)] &\leq 2 \cdot E_1 \left[T \left(\frac{n}{4} \right) \right] + \frac{1}{2} \cdot E_1 \left[T \left(\frac{n}{2} \right) \right] + a \\ &\leq 2 \cdot \left[c \left(\frac{n}{4} \right)^{\alpha} - d \right] + \frac{1}{2} \cdot \left[\left(\frac{n}{2} \right)^{\alpha} - d \right] + a \\ &= cn^{\alpha} \left(\frac{2}{4^{\alpha}} + \frac{1}{2 \cdot 2^{\alpha}} \right) + a - \frac{5d}{2} \end{split}$$

Claim: $E_1[T(n)] \le cn^{\alpha} - d$ for some c > d > 0 and all $n \ge 1$, where $\alpha = \lg\left(\frac{1+\sqrt{33}}{4}\right) \le 0.754$.

$$\begin{split} E_{l}[T(n)] &\leq 2 \cdot E_{l} \left[T \left(\frac{n}{4} \right) \right] + \frac{1}{2} \cdot E_{l} \left[T \left(\frac{n}{2} \right) \right] + a \\ &\leq 2 \cdot \left[c \left(\frac{n}{4} \right)^{\alpha} - d \right] + \frac{1}{2} \cdot \left[\left(\frac{n}{2} \right)^{\alpha} - d \right] + a \\ &= cn^{\alpha} \left(\frac{2}{4^{\alpha}} + \frac{1}{2 \cdot 2^{\alpha}} \right) + a - \frac{5d}{2} \\ &\leq cn^{\alpha} \left(\frac{2}{4^{\alpha}} + \frac{1}{2 \cdot 2^{\alpha}} \right) - d \quad \forall d \geq \frac{2}{3} a \end{split}$$

Claim: $E_1[T(n)] \le cn^{\alpha} - d$ for some c > d > 0 and all $n \ge 1$, where $\alpha = \lg\left(\frac{1+\sqrt{33}}{4}\right) \le 0.754$.

$$\begin{split} E_{I}[T(n)] &\leq 2 \cdot E_{I} \left[T \left(\frac{n}{4} \right) \right] + \frac{1}{2} \cdot E_{I} \left[T \left(\frac{n}{2} \right) \right] + a \\ &\leq 2 \cdot \left[c \left(\frac{n}{4} \right)^{\alpha} - d \right] + \frac{1}{2} \cdot \left[\left(\frac{n}{2} \right)^{\alpha} - d \right] + a \\ &= cn^{\alpha} \left(\frac{2}{4^{\alpha}} + \frac{1}{2 \cdot 2^{\alpha}} \right) + a - \frac{5d}{2} \\ &\leq cn^{\alpha} \left(\frac{2}{4^{\alpha}} + \frac{1}{2 \cdot 2^{\alpha}} \right) - d \quad \forall d \geq \frac{2}{3} a \end{split}$$

$$= cn^{\alpha} \left(\frac{2}{\left(\frac{1 + \sqrt{33}}{4} \right)^{2}} + \frac{1}{2 \cdot \frac{1 + \sqrt{33}}{4}} \right) - d$$

Claim: $E_1[T(n)] \le cn^{\alpha} - d$ for some c > d > 0 and all $n \ge 1$, where $\alpha = \lg\left(\frac{1+\sqrt{33}}{4}\right) \le 0.754$.

$$\mathsf{E}_{\mathsf{I}}[\mathsf{T}(\mathsf{n})] \leq \mathsf{cn}^{\alpha} \left(\frac{2}{\left(\frac{1+\sqrt{33}}{4}\right)^2} + \frac{1}{2 \cdot \frac{1+\sqrt{33}}{4}} \right) - \mathsf{d}$$

Claim: $E_1[T(n)] \le cn^{\alpha} - d$ for some c > d > 0 and all $n \ge 1$, where $\alpha = \lg\left(\frac{1+\sqrt{33}}{4}\right) \le 0.754$.

$$\begin{split} E_{1}[T(n)] & \leq cn^{\alpha} \left(\frac{2}{\left(\frac{1+\sqrt{33}}{4} \right)^{2}} + \frac{1}{2 \cdot \frac{1+\sqrt{33}}{4}} \right) - d \\ & = cn^{\alpha} \left(\frac{32+2 \cdot (1+\sqrt{33})}{(1+\sqrt{33})^{2}} \right) - d \end{split}$$

Claim: $E_1[T(n)] \le cn^{\alpha} - d$ for some c > d > 0 and all $n \ge 1$, where $\alpha = lg\left(\frac{1+\sqrt{33}}{4}\right) \le 0.754$.

$$\begin{split} E_{l}[T(n)] & \leq cn^{\alpha} \left(\frac{2}{\left(\frac{1 + \sqrt{33}}{4} \right)^{2}} + \frac{1}{2 \cdot \frac{1 + \sqrt{33}}{4}} \right) - d \\ & = cn^{\alpha} \left(\frac{32 + 2 \cdot (1 + \sqrt{33})}{(1 + \sqrt{33})^{2}} \right) - d \\ & = cn^{\alpha} \left(\frac{34 + 2 \cdot \sqrt{33}}{34 + 2 \cdot \sqrt{33}} \right) - d \end{split}$$

Claim: $E_1[T(n)] \le cn^{\alpha} - d$ for some c > d > 0 and all $n \ge 1$, where $\alpha = \lg\left(\frac{1+\sqrt{33}}{4}\right) \le 0.754$.

$$\begin{split} E_{1}[T(n)] &\leq cn^{\alpha} \left(\frac{2}{\left(\frac{1+\sqrt{33}}{4}\right)^{2}} + \frac{1}{2 \cdot \frac{1+\sqrt{33}}{4}} \right) - d \\ &= cn^{\alpha} \left(\frac{32+2 \cdot (1+\sqrt{33})}{(1+\sqrt{33})^{2}} \right) - d \\ &= cn^{\alpha} \left(\frac{34+2 \cdot \sqrt{33}}{34+2 \cdot \sqrt{33}} \right) - d \\ &= cn^{\alpha} - d \end{split}$$

Summary

Algorithms that are fast on average are often easier to design and faster in practice than worst-case efficient algorithms.

In some applications, worst-case guarantees matter!

Average-case analysis provides a valid performance prediction only if the inputs are uniformly distributed.

Randomized algorithms remove this dependence on the input distribution (but rely on a good random number generator).

There are problems where randomized algorithms are provably faster than the best possible deterministic algorithm.