Fundamentals of Computational Neuroscience 2e

Thomas Trappenberg

March 2, 2009

Chapter 7: Cortical maps and competitive population coding

< □ > < 同 > < 三 > < 三 > < 三 > < ○ < ○ </p>

Tuning Curves



◆□▶ ◆□▶ ◆臣▶ ◆臣▶ 三臣 - のへで

Self-organizing maps



Update rule of (recurrent) cortical network:

$$\tau \frac{\mathrm{d}u_i(t)}{\mathrm{d}t} = -u_i(t) + \frac{1}{N}\sum_j w_{ij}r_j(t) + \frac{1}{M}\sum_k w_{ik}^{\mathrm{in}}r_k^{\mathrm{in}}(t)$$

Activation function: $r_j(t) = \frac{1}{1+e^{\beta(u_j(t)-\alpha)}}$.

Lateral weight matrix: $w_{ij} \propto r_i r_j$

$$= \boldsymbol{A}_{\mathrm{w}} \left(\mathrm{e}^{-((i-j)*\Delta x)^2/2\sigma^2} - \boldsymbol{C} \right)$$

Input weight matrix: $w_{ij}^{in} \propto r_i r_j^{in}$

Shortcut



som.m

```
%% Two dimensional self-organizing feature map al la Kohonen
 1
 2
      clear; nn=10; lambda=0.2; sig=2; sig2=1/(2*sig^2);
 3
      [X,Y]=meshgrid(1:nn,1:nn); ntrial=0;
 4
 5
      % Initial centres of prefered features:
 6
      c1=0.5-.1*(2*rand(nn)-1);
 7
      c2=0.5-.1*(2*rand(nn)-1);
 8
 9
     %% training session
10
     while(true)
11
         if (mod (ntrial, 100) == 0) % Plot grid of feature centres
12
              clf; hold on; axis square; axis([0 1 0 1]);
13
             plot(c1,c2,'k'); plot(c1',c2','k');
             tstring=[int2str(ntrial) ' examples']; title(tstring);
14
15
             waitforbuttonpress;
16
         end
17
         r in=[rand;rand];
18
         r = \exp(-(c1 - r_in(1)) \cdot 2 - (c2 - r_in(2)) \cdot 2);
19
         [rmax, x_winner]=max(max(r)); [rmax, y_winner]=max(max(r'));
2.0
         r=exp(-((X-x winner).^2+(Y-v winner).^2)*sig2);
21
         c1=c1+lambda*r.*(r in(1)-c1);
2.2
         c2=c2+lambda*r.*(r in(2)-c2);
2.3
         ntrial=ntrial+1:
24
      end
```

SOM simulation



▲□▶ ▲□▶ ▲□▶ ▲□▶ = 三 のへで

Another example



Zhou and Merzenich, PNAS 2007



◆□▶ ◆□▶ ◆豆▶ ◆豆▶ □豆 の々で

Dynamic Neural Field Theory

Field dynamics:

$$\tau \frac{\partial \mathbf{u}(\mathbf{x},t)}{\partial t} = -\mathbf{u}(\mathbf{x},t) + \int_{\mathbf{y}} \mathbf{w}(\mathbf{x},\mathbf{y}) \mathbf{r}(\mathbf{y},t) \mathrm{d}\mathbf{y} + l^{\mathrm{ext}}(\mathbf{x},t)$$

$$\mathbf{r}(\mathbf{x},t)=g(\mathbf{u}(\mathbf{x},t)),$$

Continuous version of equations above with discretization:

$$x
ightarrow i \Delta x$$
 and $\int \mathrm{d} x
ightarrow \Delta x \sum$

▲□▶ ▲□▶ ▲□▶ ▲□▶ ▲□ ● のへぐ

Lateral weight kernel

$$\mathbf{w}^{\mathrm{E}}(|x-y|) = \mathbf{A}_{\mathrm{w}}\mathrm{e}^{-(x-y)^{2}/4\sigma_{r}^{2}}$$

Can be learned from Gaussian response curves of individual nodes



◆□▶ ◆□▶ ◆三▶ ◆三▶ ・三 の々で

Self-sustained activity packet



DNF example



dnf.m

```
%% Dynamic Neural Field Model (1D)
 1
 2
     clear; clf; hold on;
      nn = 100; dx=2*pi/nn; sig = 2*pi/10; C=0.5;
 3
 4
 5
     %% Training weight matrix
 6
      for loc=1:nn;
 7
          i=(1:nn)'; dis= min(abs(i-loc),nn-abs(i-loc));
 8
          pat(:,loc)=exp(-(dis*dx).^2/(2*sig^2));
9
      end
10
      w=pat*pat'; w=w/w(1,1); w=4*(w-C);
11
     %% Update with localised input
12
     tall = []; rall = [];
1.3
     I ext=zeros(nn,1); I ext(nn/2-floor(nn/10):nn/2+floor(nn/10))=1;
14
     [t,u]=ode45('rnn_ode',[0 10],zeros(1,nn),[],nn,dx,w,I_ext);
15
      r=1./(1+exp(-u)); tall=[tall;t]; rall=[rall;r];
     %% Update without input
16
17
     I ext=zeros(nn,1);
18
     [t,u]=ode45('rnn ode', [10 20],u(size(u,1),:),[],nn,dx,w,I ext);
19
      r=1./(1+exp(-u)); tall=[tall;t]; rall=[rall;r];
20
     %% Plotting results
21
      surf(tall',1:nn,rall','linestyle','none'); view(0,90);
```

rnn_ode.m

```
1 function udot=rnn_ode(t,u,flag,nn,dx,w,I_ext)
2 % odefile for recurrent network
3 tau_inv = 1.; % inverse of membrane time constant
4 r=1./(l+exp(-u));
5 sum=w*r*dx;
6 udot=tau_inv*(-u+sum+I_ext);
7 return
```

Update rule of (recurrent) cortical network:

$$\tau \frac{du_{i}(t)}{dt} = -u_{i}(t) + \frac{1}{N} \sum_{i} w_{ij}r_{j}(t) + \frac{1}{M} \sum_{k} w_{ik}^{in}r_{k}^{in}(t)$$

< □ > < 同 > < 三 > < 三 > < 三 > < ○ < ○ </p>

Activation function: $r_j(t) = \frac{1}{1+e^{\beta(u_j(t)-\alpha)}}$.

Path integration



Node index i

▲□▶ ▲□▶ ▲□▶ ▲□▶ = 三 のへで

Population coding

Probability of neural response for a sensory input: $P(\mathbf{r}|s) = P(r_1^s, r_2^s, r_3^s, ...|s)$

Decoding: $P(s|\mathbf{r}) = P(s|r_1^s, r_2^s, r_3^s, ...)$

Stimulus estimate: $\hat{s} = \arg \max_{s} P(s|\mathbf{r})$

Bayes's theorem: $P(s|\mathbf{r}) = \frac{P(\mathbf{r}|s)P(s)}{P(\mathbf{r})}$

Maximum likelihood estimate: $\hat{s} = \operatorname{argmin} \sum_{i} \left(\frac{r_i - f_i(s)}{\sigma_i} \right)^2$

Implementations of decoding mechanisms with DNF



◆□▶ ◆□▶ ◆豆▶ ◆豆▶ □ のへで

Further Readings

Teuvo Kohonen (1989), Self-organization and associative memory, Springer Verlag, 3rd edition.

- David J. Willshaw and Christoph von der Malsburg (1976), How patterned neural connexions can be set up by self-organisation, in Proc Roy Soc B 194, 431–445.
- Shun-ichi Amari (1977), Dynamic pattern formation in lateral-inhibition type neural fields, in Biological Cybernetics 27: 77-87.
- Huge R. Wilson and Jack D. Cowan (1973), A mathematical theory of the functional dynamics of cortical and thalamic nervous tissue, in Kybernetik 13:55-80.
- Kechen Zhang (1996), Representation of spatial orientation by the intrinsic dynamics of the head-direction cell ensemble: A theory, in Journal of Neuroscience 16: 2112–2126.
- Simon M. Stringer, Thomas P. Trappenberg, Edmund T. Rolls, and Ivan E.T. de Araujo (2002), Self-organizing continuous attractor networks and path integration I: One-dimensional models of head direction cells, in Network: Computation in Neural Systems 13:217–242.
- Alexandre Pouget, Richard S. Zemel, and Peter Dayan (2000), Information processing with population codes, in Nature Review Neuroscience 1:125–132.

▲□▶▲□▶▲□▶▲□▶ □ のQ@