The Distance 4-Sector of Two Points is Unique

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Abstract. The (distance) k-sector is a generalization of the concept of bisectors proposed by Asano, Matoušek and Tokuyama. We prove the uniqueness of the 4-sector of two points in the Euclidean plane. Despite the simplicity of the unique 4-sector (which consists of a line and two parabolas), our proof is quite non-trivial. We begin by establishing uniqueness in a small region of the plane, which we show may be perpetually expanded afterward.

Keywords: distance k-sector, Tarski fixed point, uniqueness

1 Introduction

The bisector of two nonempty sets X and Y in \mathbb{R}^2 is defined as

$$\operatorname{bisect}(X,Y) = \{ z \in \mathbb{R}^2 : \operatorname{dist}(z,X) = \operatorname{dist}(z,Y) \}, \tag{1}$$

where $\operatorname{dist}(z, X) = \inf_{x \in X} \operatorname{dist}(z, x)$ denotes the Euclidean distance of z from a set X. For any integer $k \geq 2$, a distance k-sector (or simply k-sector) of distinct points $p, q \in \mathbb{R}^2$ is a (k-1)-tuple (C_1, \ldots, C_{k-1}) of nonempty subsets of \mathbb{R}^2 such that

$$C_i = \text{bisect}(C_{i-1}, C_{i+1}), \qquad i = 1, \dots, k-1,$$
 (2)

where $C_0 = \{p\}$ and $C_k = \{q\}$.

For example, there is a 4-sector of two points that consists of a line and two parabolas (Fig. 1). We will prove that this is the only one:

Theorem 1. The 4-sector between two points in the Euclidean plane is unique.

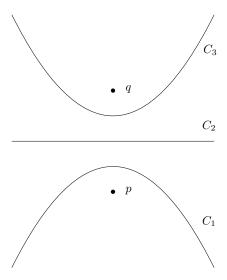


Fig. 1. A 4-sector (C_1, C_2, C_3) of p and q (whose uniqueness we will prove). If p = (0, -1) and q = (0, 1), these curves are the graphs of $y = \pm (x^2 + 1)/2$ and y = 0.

The notion of distance k-sectors was introduced by Asano and Tokuyama [4] in 2004, motivated by a question about circuit board design. Asano, Matoušek and Tokuyama [3] showed the existence and uniqueness of the 3-sector (trisector). Despite the simple definition, k-sectors (with the exception of k=2,4) do not seem to be easy to construct (note that bisecting between the curves in Fig. 1 does *not* give an 8-sector). In particular, the 3-sector is not algebraic, as conjectured in [3] and recently proved by Monterde and Ongay [8].

Although the original proof in [3] of the existence and uniqueness of the 3-sector was rather involved, it turned out later that k-sectors exist in a fairly general setting and for a relatively simple reason: Reem and Reich [9] used the Tarski fixed point theorem to prove the existence of a closely related object called double zone diagrams. Applying this idea, Imai et al. [6] proved the existence of a k-sector for any k on any sets P, Q (instead of $\{p\}$, $\{q\}$), and for a general class of metric spaces. The existence proofs sometimes suggest an algorithm to compute (draw on a screen approximately) k-sectors, but its efficiency is unclear. Some issues in computing k-sectors and double zone diagrams are discussed in [6, 10] (of course, such issues are trivial in our setting of 4-secting two points, once we show that the only 4-sector is the one explicitly given in Fig. 1).

Uniqueness is harder to prove. The uniqueness of the 3-sector was extended to the case where one of P, Q is a line segment instead of a point [5], and then to the general case where P, Q can be any disjoint nonempty closed sets [7] (in fact, they proved the uniqueness of the zone diagram [2], a generalization of 3-sectors where we start with many sets instead of just two sets P, Q). Unlike existence, uniqueness relies on the properties of the Euclidean norm, and indeed fails for, say, the l_1 norm [1, 7]. It remains open [6, Conjecture] whether k-sectors, for

 $k \ge 4$, are unique even in the Euclidean plane. Theorem 1 answers this for k = 4 (and points p, q).

Proof idea. Roughly speaking, the central part of our proof (Lemma 3) is based on the following ideas. Suppose that there are two different k-sectors $(C_i)_i$ and $(\hat{C}_i)_i$ (here and in the sequel, the subscript i always ranges over $1, \ldots, k-1$, so that $(C_i)_i$ means (C_1, \ldots, C_{k-1}) . Then there is a gap somewhere between the curves C_i and \hat{C}_i . Since they both satisfy equation (2), we must have another gap somewhere between C_{i-1} and \hat{C}_{i-1} or between C_{i+1} and \hat{C}_{i+1} , which is not too small compared to the original gap. From some observations about the size and location of the new gap, we derive contradiction by arguing that this process of finding a new gap cannot go on forever because it causes the gap to grow too big to fit where it must be. This rough intuition is common to the proof of 3-sector uniqueness in [7], but there is a lot of room for creativity as to how we define the size of the gap between two curves at a point. The proof in [7] used a clever way to measure the gap under which the gap always grows bigger, but this measure of the gaps only makes sense for 3-sectors. We measure the gap much more simply, by the difference between the v-coordinates of the two curves at a common x-coordinate. The downside is that under this measure, the gap gets bigger only when the involved parts of the curves lie in certain configuration. This necessitates some detailed argument that certain part of 4-sector indeed has this configuration (Lemma 6) and that the uniqueness of this part of the 4-sector can then be extended gradually to other parts (Lemmas 4 and 5).

2 Preliminaries: Gradations

In the definition of k-sectors above, the components C_i are sets satisfying certain equations, and we did not even say that they are curves. It is not entirely obvious, although it is true, that each of them divides the plane into two regions, one containing p and the other containing q. Imai et al. [6] made this claim precise (as Lemma 1 below) by introducing k-gradations. We briefly review their definition, as we also find k-gradations easier to reason with than k-sectors.

For nonempty $X, Y \subseteq \mathbb{R}^2$, we define the dominance region of X over Y by

$$dom(X,Y) = \{ z \in \mathbb{R}^2 : dist(z,X) \le dist(z,Y) \}.$$
 (3)

It is not hard to see [6, Lemma 6] that, if X and Y are disjoint closed sets, bisect(X,Y) is the boundary of dom(X,Y). A k-gradation between points p, $q \in \mathbb{R}^2$ is a (k-1)-tuple $(R_i,S_i)_i$ of pairs of subsets of \mathbb{R}^2 satisfying

$$R_i = \text{dom}(R_{i-1}, S_{i+1}), \quad S_i = \text{dom}(S_{i+1}, R_{i-1}), \quad i = 1, \dots, k-1,$$
 (4)

where $R_0 = \{p\}$ and $S_k = \{q\}$. It is easy to see that this implies $R_i \cup S_i = \mathbb{R}^2$, $\{p\} = R_0 \subseteq R_1 \subseteq \cdots \subseteq R_{k-1} \text{ and } S_1 \supseteq S_2 \supseteq \cdots \supseteq S_k = \{q\}$.

By the following lemma (a special case of [6, Proposition 2]), a k-sector $(C_i)_i$ can be identified with a k-gradation $(R_i, S_i)_i$:

Lemma 1 ([6]). A (k-1)-tuple $(C_i)_i$ of sets is a k-sector of points $p, q \in \mathbb{R}^2$ if and only if

$$C_i = R_i \cap S_i, \qquad i = 1, \dots, k - 1 \tag{5}$$

for some k-gradation $(R_i, S_i)_i$ between p, q.

Imai et al. [6, Proposition 1] established the existence of a k-sector by proving the existence of a k-gradation:

Lemma 2 ([6]). There exists a k-gradation between two distinct points in \mathbb{R}^2 . In fact, there are the greatest and the least k-gradations under the order defined by: $(R_i, S_i)_i \leq (R'_i, S'_i)_i$ if $R_i \subseteq R'_i$ and $S_i \supseteq S'_i$ for all i = 1, ..., k-1.

In what follows, we will primarily deal with k-gradations as opposed to k-sectors, as their use allows the proofs to be simpler and cleaner.

3 Proof of Theorem 1

For the rest of the paper, we fix p = (0, -1) and q = (0, +1) and consider the 4-sectors and 4-gradations between them. As explained above (Lemma 1), each 4-sector $(C_i)_i$ corresponds to a 4-gradation $(R_i, S_i)_i$. We will prove that this 4-gradation agrees with $(\hat{R}_i, \hat{S}_i)_i$, the trivial 4-gradation corresponding to the trivial 4-sector $(\hat{C}_i)_i$ described in Fig. 1.

Define the (closed) regions I_{β} and J_{β} , for $\beta > 0$, as follows (Fig. 2), using the trivial 4-sector $(\hat{C}_i)_i$. Consider the normal lines to the parabolas \hat{C}_1 and \hat{C}_3 at $x = \pm \beta$. The closed, finite region of the plane (containing the origin) defined by these lines is I_{β} . The region J_{β} contains I_{β} , as well as all points lying above the upper envelope of the normal lines to \hat{C}_1 and all points lying below the lower envelope of the normal lines to \hat{C}_3 . Calculation shows that the four vertices of I_{β} are $(\pm (3 + \beta^2)\beta/2, 0)$ and $(0, \pm (3 + \beta^2)/2)$.

We prove Theorem 1 using the following three lemmas. Note that the number 0.5774 in the lemmas is slightly greater than $1/\sqrt{3}$, so that the boundary halflines of $J_{0.5774}$ make angle slightly less than $\pi/3$ with the x-axis.

Lemma 3. Let $(R_i, S_i)_i$ be a 4-gradation. Then R_2 and S_2 agree with the trivial 4-gradation on $J' := J_{0.5774} \cap (\mathbb{R} \times [-4, 4])$, i.e., $R_2 \cap J' = \hat{R}_2 \cap J'$ and $S_2 \cap J' = \hat{S}_2 \cap J'$.

Lemma 4. Let $\beta \geq 0.5774$. Let $(R_i, S_i)_i$ be a 4-gradation. Suppose that R_2 and S_2 agree with the trivial 4-gradation on J_{β} , i.e., $R_2 \cap J_{\beta} = \hat{R}_2 \cap J_{\beta}$ and $S_2 \cap J_{\beta} = \hat{S}_2 \cap J_{\beta}$. Then R_1 , S_1 , R_3 , S_3 agree with the trivial 4-gradation on a region $I_{\beta'}$, for some $\beta' \geq 1.00001\beta$. Moreover, for $\beta = 0.5774$, this holds with J_{β} replaced by the J' defined in Lemma 3.

Lemma 5. Let $\beta > 0$. Let $(R_i, S_i)_i$ be a 4-gradation. Suppose that R_1, S_1, R_3, S_3 agree with the trivial 4-gradation on I_{β} , i.e., $R_i \cap I_{\beta} = \hat{R}_i \cap I_{\beta}$ and $S_i \cap I_{\beta} = \hat{S}_i \cap I_{\beta}$ for each i = 1, 3. Then R_2, S_2 agree with the trivial 4-gradation on J_{β} , i.e., $R_2 \cap J_{\beta} = \hat{R}_2 \cap J_{\beta}$ and $S_2 \cap J_{\beta} = \hat{S}_2 \cap J_{\beta}$.

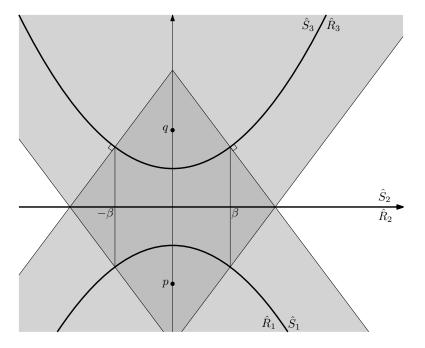


Fig. 2. Closed regions I_{β} (dark grey) and J_{β} (light grey plus dark grey), defined from the trivial 4-gradation $(\hat{R}_i, \hat{S}_i)_i$.

Lemma 3 is the central part of our proof: it says that the middle component (R_2, S_2) of the 4-gradation is uniquely determined (and agrees with the trivial one) up to a certain point (i.e., in the region J'). Lemma 4 says that if (R_2, S_2) is uniquely determined up to some point, then it uniquely determines (R_1, S_1) and (R_3, S_3) up to some point. Lemma 5 works the other way, stating that a certain part of (R_2, S_2) is determined by certain parts of (R_1, S_1) and (R_3, S_3) .

To prove Theorem 1, we use Lemma 3 followed by the last sentence (the "moreover" part) of Lemma 4, and then apply Lemmas 5 and 4 alternately, extending step by step the region on which the considered 4-gradation agrees with the trivial one. This proves the uniqueness of the 4-gradation, and thus, by Lemma 1, of the 4-sector.

The proofs of the lemmas require a number of additional properties, and so their presentation is delayed to Sections 3.2 and 3.3.

3.1 Properties of a 4-Gradation

Before proving the lemmas, we need to get some rough estimates about what a 4-gradation must look like. Let B(w,r) (resp. $B^{\circ}(w,r)$) denote the closed (resp. open) ball with centre w and radius r.

Lemma 6. Let $(R_i, S_i)_i$ be a 4-gradation. Then

- 1. R_1 and S_3 are convex.
- 2. $\operatorname{dist}(R_i, S_{i+1}) \ge 1/2$ for each i = 0, 1, 2, 3.
- 3. $B(p, i/2) \subseteq R_i$ and $B(q, i/2) \subseteq S_{4-i}$ for each i = 0, 1, 2, 3, 4.
- 4. $R_1 \subseteq \mathbb{R} \times (-\infty, -1/2]$ and $S_3 \subseteq \mathbb{R} \times [1/2, \infty)$.
- 5. Let w = (a, b) be a point with $a \ge 0$ and $b \le 0$. Let v = (a', b') be a closest point to w in S_3 . Then,
 - (a) $0 \le a' \le a$.
 - (b) If $|a| \le 1.16$, then $b' \in [1/2, 0.82]$.
- Likewise for S_3 and $b \leq 0$ replaced by R_1 and $b \geq 0$, respectively. 6. For each t > 0, let $L_t^{\pm} = \{(x,y) \in \mathbb{R}^2 : \pm y \leq x^2/t\}$, respectively. Then $R_2 \subseteq L_4^+$ and $S_2 \subseteq L_4^-$.

Proof. 1. $R_1 = \text{dom}(p, S_2) = \bigcap_{s \in S_2} \text{dom}(p, s)$, and the right-hand side is an intersection of halfspaces. Similarly for S_3 .

- 2. Otherwise, there exists an i such that $dist(x_i, x_{i+1}) < 1/2$ for some $x_i \in$ R_i and $x_{i+1} \in S_{i+1}$. By redefining x_i and x_{i+1} on the segment $x_i x_{i+1}$ if necessary, we have $x_i \in R_i \cap S_i$ and $x_{i+1} \in R_{i+1} \cap S_{i+1}$. Starting from this, we can inductively obtain a point $x_j \in R_j \cap S_j$ with $\operatorname{dist}(x_j, x_{j+1}) < 1/2$ for each $j = i-1, i-2, \ldots, 0$; and a point $x_j \in R_j \cap S_j$ with $\operatorname{dist}(x_{j-1}, x_j) < 1/2$ for each $j = i + 2, i + 3, \ldots, 4$. Thus p and q are connected by a path $x_0x_1x_2x_3x_4$ of length less than $4 \times 1/2$, a contradiction.
- 3. We prove the first claim by induction on i (the second claim is analogous). By part 2 and the induction hypothesis, $S_{i+1} \subseteq \mathbb{R}^2 \setminus B^{\circ}(p,(i+1)/2)$. By this and $R_{i+1} \cup S_{i+1} = \mathbb{R}^2$, we have $R_{i+1} \supseteq B^{\circ}(p, (i+1)/2)$. Since R_{i+1} is closed, $R_{i+1} \supseteq B(p, (i+1)/2)$.
- 4. Since $(0,0) \in S_2$ by part 3, we have $R_1 = \text{dom}(\{p\}, S_2) \subseteq \text{dom}(\{p\}, (0,0)) =$ $\mathbb{R} \times (-\infty, -1/2]$. Similarly for S_3 .
- 5. Since S_3 is convex by part 1, it is contained in the (closed) halfplane H_w defined as the opposite side from w across the perpendicular of vw at v. Since H_w contains B(q, 1/2) by part 3, and the point v on its boundary is in $\mathbb{R} \times [1/2, \infty)$ by part 4, it must be the case that $0 \le a' \le a$.

We will prove the other claim, $b' \leq 0.82$. It suffices to show this for the case where w is the upper-right-most point $w_0 = (1.16, 0)$. To see why, let $v_0 = (a'_0, b'_0)$ be a closest point in S_3 to w_0 , and define the halfplane H_{w_0} in the same way as H_w from w_0 and v_0 . Since H_{w_0} contains w and H_w contains w_0 , they must coincide. So v must be at the same relative position from v_0 as w is from w_0 , and thus must lie below, i.e., $b' \leq b'_0$.

Thus our goal now is to show $b'_0 \leq 0.82$. Recall that H_{w_0} contains B(q, 1/2). The line tangent to the lower half of the ball B(q, 1/2) at the point with x-coordinate x_0 is described as

$$y = \frac{x_0}{\sqrt{1/4 - x_0^2}} x + \frac{\sqrt{1/4 - x_0^2 - 1/4}}{\sqrt{1/4 - x_0^2}} . \tag{6}$$

Similarly, the line perpendicular to this tangent and passing through w_0 is

$$y = -\frac{\sqrt{1/4 - x_0^2}}{x_0}x + \frac{1.16\sqrt{1/4 - x_0^2}}{x_0} \ . \tag{7}$$

These lines intersect at

$$x = \frac{1.16/4 + x_0/4 - 1.16x_0^2 - x_0\sqrt{1/4 - x_0^2}}{1/4 + x_0^2} \ . \tag{8}$$

Using substitution and a numerical calculation we get that the maximum y-value achieved by this intersection point over the domain $x_0 \in (0, 1/2)$ is 0.819534... < 0.82 at $x_0 = 0.243934...$ This value bounds b'_0 from above.

6. By parts 3 and 4, $R_2 = \text{dom}(R_1, S_3) \subseteq \text{dom}(\mathbb{R} \times (-\infty, -1/2], B(q, 1/2)) = \text{dom}(\mathbb{R} \times (-\infty, -1]), \{q\}) = L_4^+$. Similarly for S_2 .

In the rest of this paper, part x of Lemma 6 is referred to as Lemma 6.x.

3.2 Proof of Lemma 3: Uniqueness Near the Origin

We now prove Lemma 3. Recall the statement:

Lemma 3. Let $(R_i, S_i)_i$ be a 4-gradation. Then R_2 and S_2 agree with the trivial 4-gradation on $J' := J_{0.5774} \cap (\mathbb{R} \times [-4, 4])$, i.e., $R_2 \cap J' = \hat{R}_2 \cap J'$ and $S_2 \cap J' = \hat{S}_2 \cap J'$.

Proof. We may assume that $(R_i, S_i)_i$ is the greatest 4-gradation in the sense of Lemma 2 (the same argument works for the least gradation by symmetry, and proves that the greatest and least gradations, and hence all gradations, coincide on J'). This implies that $R_i \supseteq \hat{R}_i$ and $S_i \subseteq \hat{S}_i$ for each i. It suffices to prove that $R_2 \cap J' \subseteq \hat{R}_2 \cap J'$. Suppose otherwise, i.e., that $R_2 \cap J'$ contains a point above the x-axis. Then the set of t > 0 with $L_t^+ \supseteq R_2 \cap J'$ (see Lemma 6.6 for the definition of L_t^+) is bounded from above. This set is closed, and contains 4 by Lemma 6.6, so it has a maximum, which we call t from now on. By the maximality of t, there is a point t is on the boundary of t. We assume without loss of generality that t is 0. Calculation shows that the right uppermost point of t is t in t in

Thus, we are looking at the point $w \in R_2 \cap J'$ that lies on the boundary of L_t^+ . Below, we will split into two cases, and argue that in either case we can find another point $u \in R_2 \cap J'$ that does not belong to L_t^+ , contradicting the way we defined t. Let $l := \operatorname{dist}(w, R_1) = \operatorname{dist}(w, S_3)$ and $\hat{l} := \operatorname{dist}(\hat{w}, \hat{R}_1) = \operatorname{dist}(\hat{w}, \hat{S}_3)$.

Case 1: $l \leq \hat{l}$. Define v to be the closest point to w in R_1 , and let $\hat{v} := v - (0, \varepsilon)$ (Fig. 3). Since $\operatorname{dist}(\hat{w}, \hat{v}) = \operatorname{dist}(w, v) = l$, we have $\hat{v} \in \operatorname{B}(\hat{w}, l) \subseteq \operatorname{B}(\hat{w}, \hat{l}) \subseteq \hat{S}_1$.

Let $h := \operatorname{dist}(v, S_2)$ and $\hat{h} := \operatorname{dist}(\hat{v}, \hat{S}_2)$. Since $v \in \mathbb{R} \times [-0.82, 0.82]$ by Lemma 6.5b, and $\varepsilon < 0.34$, we have $h = \operatorname{dist}(v, p) > \operatorname{dist}(\hat{v}, p) \ge \hat{h}$.

Define \hat{u} to be the closest point to \hat{v} in \hat{S}_2 and let $u := \hat{u} + (0, \varepsilon) = (a', \varepsilon)$. Thus, u and \hat{u} are vertically aligned with \hat{v} . Since $\operatorname{dist}(v, u) = \operatorname{dist}(\hat{v}, \hat{u}) = \hat{h} < h$, the point u belongs to R_2 and is different from w (because $\operatorname{dist}(v, w) \geq h$). By Lemma 6.5a, it lies on the left of w, which was in J' and on the boundary of L_t^+ . Hence, $u \in J' \setminus L_t^+$, contradicting $R_2 \cap J' \subseteq L_t^+$.

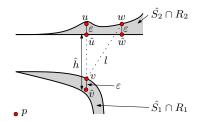


Fig. 3. Illustration of Case 1 from the proof of Lemma 3.

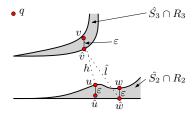


Fig. 4. Illustration of Case 2 from the proof of Lemma 3.

Case 2: $l \ge \hat{l}$. Define \hat{v} to be the closest point to \hat{w} in \hat{S}_3 , and let $v := \hat{v} + (0, \varepsilon)$ (Fig. 4). Since $\operatorname{dist}(w, v) = \operatorname{dist}(\hat{w}, \hat{v}) = \hat{l}$, we have $v \in B(w, \hat{l}) \subseteq B(w, l) \subseteq R_3$.

Let $h := \operatorname{dist}(v, R_2)$ and $\hat{h} := \operatorname{dist}(\hat{v}, \hat{R}_2)$. Since $\hat{v} \in \mathbb{R} \times [-0.82, 0.82]$ by Lemma 6.5b, and $\varepsilon < 0.34$, we have $h \leq \operatorname{dist}(v, q) < \operatorname{dist}(\hat{v}, q) = \hat{h}$.

Define u to be the closest point (or one of the closest points) to v in R_2 , and let $\hat{u} = u - (0, \varepsilon)$. Since $w \in J' \cap R_2 \subseteq J' \cap L_4^+$ by Lemma 6.6, the point v is in the region V in Fig. 5. Calculation shows that V does not intersect dom($\mathbb{R}^2 \setminus J'$, $\{q\}$). In particular, dist $(v, \mathbb{R}^2 \setminus J') > \text{dist}(v, q) \ge h = \text{dist}(v, u)$. Hence $u \in J'$.

Again, our goal is to prove $u \notin L_t^+$, thus contradicting $R_2 \cap J' \subseteq L_t^+$. Note that $u \in \mathrm{B}(v,\hat{l})$, because u is a closest point to v in R_2 , and hence closer than w. Note also that $u \in \mathbb{R} \times (\varepsilon, \infty)$, because \hat{u} lies in the interior of $\mathrm{B}(\hat{v},\hat{h}) \subseteq \hat{S}_2$ by $\mathrm{dist}(\hat{v},\hat{u}) = \mathrm{dist}(v,u) = h < \hat{h}$. Thus, it suffices to prove that the three regions L_t^+ , $\mathrm{B}(v,\hat{l})$ and $\mathbb{R} \times (\varepsilon, \infty)$ do not intersect. We argue as follows.

Notice that the boundaries of these three regions all pass through w. At this point w, the boundary of $\mathrm{B}(v,\hat{l})$ has slope b, where b is the x-coordinate of \hat{v} and v, and the boundary of L_t^+ has slope 2a/t, which is smaller than b because $a=(3+b^2)b/2<2b$ and $t\geq 4$. And also on the right of w, the slope of the boundary of $\mathrm{B}(v,\hat{l})$ continues to be greater than that of L_t^+ , because the curvature of the former is greater than that of the latter by $\hat{l}\leq \mathrm{dist}((1.16,0),\hat{S}_3)=0.874\ldots<1$. Hence, the boundaries of $\mathrm{B}(v,\hat{l})$ and L_t^+ never meet on the right of w, so the intersection $\mathrm{B}(v,\hat{l})\cap L_t^+$ lies entirely below w, and thus misses $\mathbb{R}\times(\varepsilon,\infty)$. \square

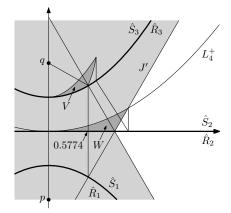


Fig. 5. The light-shaded region is J'. Since the point w is in the region $W = L_4^+ \cap \hat{S}_2 \cap J'$, the point v (obtained from w by way of \hat{w} and \hat{v} as described in Case 2 of the proof of Lemma 3) is in the region V (defined by suitable algebraic curves).

3.3 Proof of Lemmas 4 and 5: Extending Uniqueness

We define an additional closed region K_{β} . The boundaries of K_{β} are line segments which are positioned at angles of $\pm \pi/3$ with respect to the x-axis and intersect the boundary of I_{β} on the x-axis, so the vertices bounding K_{β} are $(\pm (3 + \beta^2)\beta/2, 0)$ and $(0, \pm (3 + \beta^2)\sqrt{3}\beta/2)$. Note $I_{\beta} \subset K_{\beta}$ when $\beta > 1/\sqrt{3}$. Recall Lemma 4:

Lemma 4. Let $\beta \geq 0.5774$. Let $(R_i, S_i)_i$ be a 4-gradation. Suppose that R_2 and S_2 agree with the trivial 4-gradation on J_{β} , i.e., $R_2 \cap J_{\beta} = \hat{R}_2 \cap J_{\beta}$ and $S_2 \cap J_{\beta} = \hat{S}_2 \cap J_{\beta}$. Then R_1 , S_1 , R_3 , S_3 agree with the trivial 4-gradation on a region $I_{\beta'}$, for some $\beta' \geq 1.00001\beta$. Moreover, for $\beta = 0.5774$, this holds with J_{β} replaced by the J' defined in Lemma 3.

Proof. Let $z \in K_{\beta}$. We demonstrate that $K_{\beta} \cap R_1 = K_{\beta} \cap \hat{R}_1$; the argument is similar for S_1 , R_3 , S_3 . The condition $\beta \geq 0.5774 > 1/\sqrt{3}$ ensures that the lines delimiting J_{β} have slope smaller (in absolute value) than $\sqrt{3}$, so that any point in K_{β} is closer to $\hat{S}_2 \cap J_{\beta}$ (which coincides with $S_2 \cap J_{\beta}$) than to $\mathbb{R}^2 \setminus J_{\beta}$. So the nearest point to z in S_2 is in J_{β} . Hence

$$\operatorname{dist}(z, S_2) = \operatorname{dist}(z, S_2 \cap J_\beta) = \operatorname{dist}(z, \hat{S}_2 \cap J_\beta) = \operatorname{dist}(z, \hat{S}_2). \tag{9}$$

So $z \in R_1$ if and only if $z \in \hat{R}_1$. Since z was an arbitrary element of K_β , we have $K_\beta \cap R_1 = K_\beta \cap \hat{R}_1$.

Define β' to be the absolute value of the x-coordinate of an intersection point of R_1 (or equivalently \hat{R}_1) with the boundary of K_{β} . Since R_1 is convex, it cannot contain a point in $I_{\beta'} \setminus K_{\beta}$, and thus $I_{\beta'} \cap R_1 = I_{\beta'} \cap \hat{R}_1$.

It remains to prove $\beta' \geq 1.00001\beta$. To express β' in terms of β , it suffices to equate the expressions for C_1 and the boundary of K_{β} and solve for the roots:

$$\beta' = -\sqrt{3} + \sqrt{2 + \sqrt{3}\beta^3 + 3\sqrt{3}\beta}.$$
 (10)

Finally, it may be shown that $\sigma' \ge 1.00001\sigma$ for $\sigma' := \sqrt{3}\beta'$ and $\sigma := \sqrt{3}\beta \ge 0.5774\sqrt{3} \ge 1.00001^8$. Calculation shows that

$$\sigma' = -3 + \sqrt{6 + 9\sigma + \sigma^3} \ge -3 + (3 + \sigma^{9/8}) = \sigma^{1/8} \cdot \sigma \ge 1.00001\sigma, \tag{11}$$

where the first inequality holds because $(6+9\sigma+\sigma^3)-(3+\sigma^{9/8})^2=3(\sigma-1)+\sigma(\sigma^{10/8}+\sigma^{11/8}+\sigma^{12/8}+\sigma^{13/8}+\sigma^{14/8}+\sigma^{15/8}-6)(\sigma^{1/8}-1)\geq 0$.

For the final statement of the lemma (the "moreover" part), note that if $\beta = 0.5774$, then $(3 + \beta^2)\sqrt{3}\beta/2 < 1.66$. Thus, $K_{0.5774} \subset \mathbb{R} \times [-1.66, 1.66]$, and so points in $J_{0.5774} \setminus J'$ are irrelevant.

Finally, we prove Lemma 5. Recall its statement:

Lemma 5. Let $\beta > 0$. Let $(R_i, S_i)_i$ be a 4-gradation. Suppose that R_1, S_1, R_3, S_3 agree with the trivial 4-gradation on I_{β} , i.e., $R_i \cap I_{\beta} = \hat{R}_i \cap I_{\beta}$ and $S_i \cap I_{\beta} = \hat{S}_i \cap I_{\beta}$ for each i = 1, 3. Then R_2, S_2 agree with the trivial 4-gradation on J_{β} , i.e., $R_2 \cap J_{\beta} = \hat{R}_2 \cap J_{\beta}$ and $S_2 \cap J_{\beta} = \hat{S}_2 \cap J_{\beta}$.

Proof. Let $z \in J_{\beta}$. Because R_1 is convex (Lemma 6.1) and agrees with \hat{R}_1 on I_{β} , the nearest point to z in R_1 is in I_{β} . Hence

$$\operatorname{dist}(z, R_1) = \operatorname{dist}(z, R_1 \cap I_\beta) = \operatorname{dist}(z, \hat{R}_1 \cap I_\beta) = \operatorname{dist}(z, \hat{R}_1), \tag{12}$$

and likewise

$$\operatorname{dist}(z, S_3) = \operatorname{dist}(z, S_3 \cap I_\beta) = \operatorname{dist}(z, \hat{S}_3 \cap I_\beta) = \operatorname{dist}(z, \hat{S}_3). \tag{13}$$

So $z \in S_2$ if and only if $z \in \hat{S}_2$. Since z was an arbitrary element of J_β , we have $J_\beta \cap S_2 = J_\beta \cap \hat{S}_2$. Similarly for R_2 .

This completes the proof of Theorem 1.

4 Conclusions

We have shown that the 4-sector of two points is unique. Although we tried our best to simplify our proof, we still find it frustrating (and intriguing) that the uniqueness of such a seemingly basic object needed several pages to prove. As mentioned in the introduction, the main idea was to argue that if there are two k-sectors that differ at some point, there must be another point where they differ "more", in terms of some measure of the difference. But to implement this idea, we had to resort to calculation that relied heavily on the special setting of k=4 and P,Q being points. It would be nice if this tedious calculation could be replaced by a conceptually simpler argument that works in more general settings.

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